



LAGO INDICA

EOSC, MEIGA y Muongrafía

Hernán Asorey^{1,2} for the LAGO Collaboration

BGA, Colombia, 20/Nov/2024

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outline

1. Some basis about HPC and cloud
2. Data standardization
3. LAGO EOSC Implementation
4. LAGO WCD Application in Meiga
5. Hodoscope Application in MEIGA

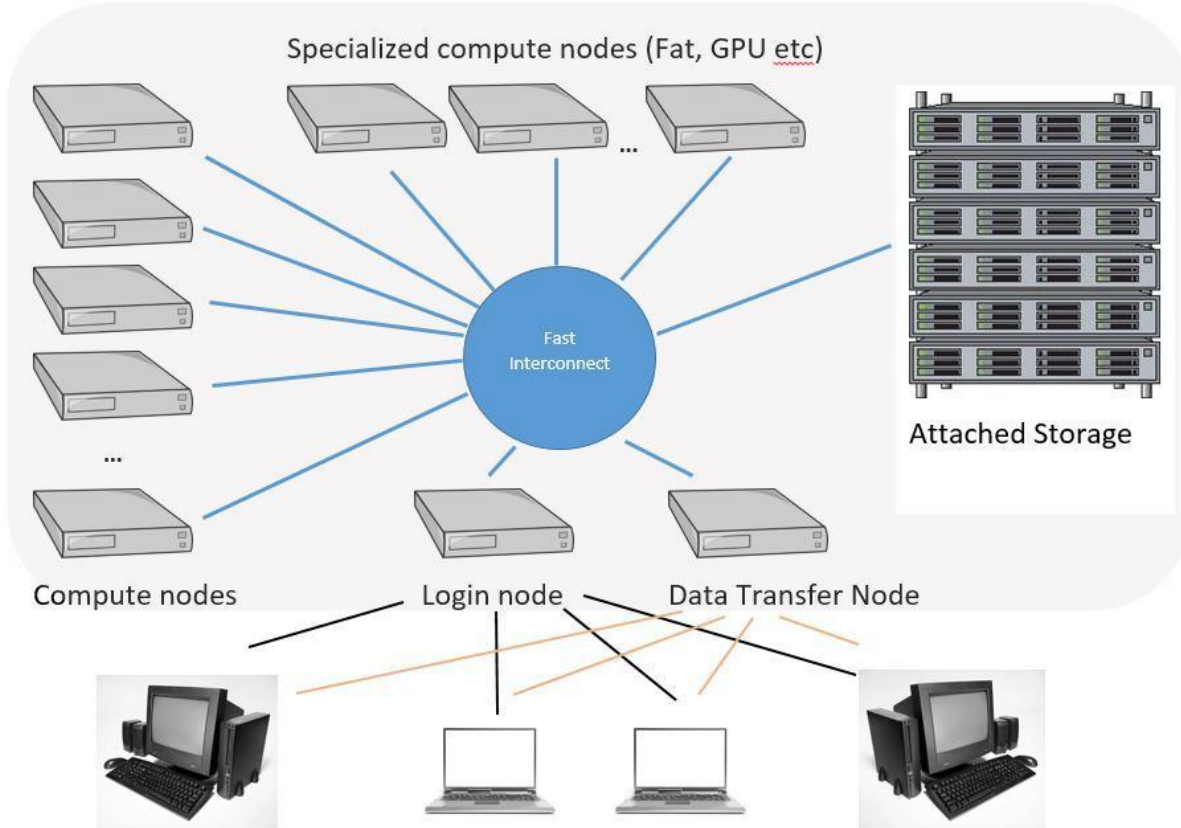
clusters, nodos, cpu, and their v-relatives

Cluster?

Node?

CPU?

Process?



A computer cluster is a collective of individual computers yoked together so they function like a single entity for a variety of tasks

High Performance Computing



core or processor

Processor cores are individual processing units within the central processing unit (CPU) + Core memory cache (kiB). Each core is capable to perform individual tasks

processor or core <- always is the CPU

Processing power. The more powerful and updated your processor, the faster your computer can complete its tasks.

(multi)-core (c cores) + some fast access memory caches (MiB)

node

*an individual computer with p processors with c cores each one, so $(p*c)$ is the total number of cores) + local disk storage (TiB) + local memory (GiB)*

cluster

A computer cluster is a collective of individual nodes (computers) yoked together so they work as a single entity for a variety of tasks. A core could have f front-end nodes + n nodes + distributed memory (TiB) + distributed storage (PiB)

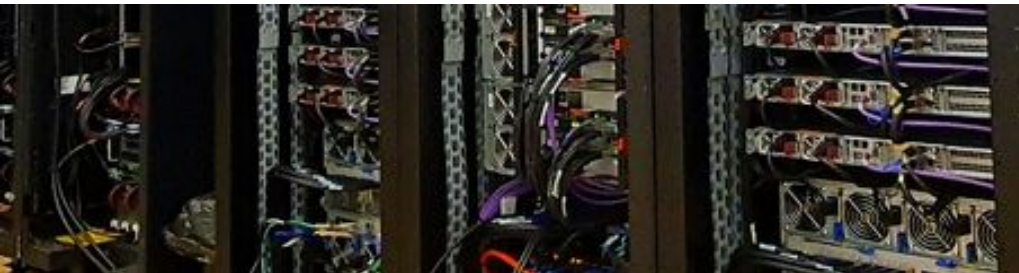
cluster: Marenostrom 4 (BSC)



cluster: Marenostrom 5 (BSC)



Turgalium, ACME, XULA



TurboLinux ACME VIII A



Nombre de la máquina	Xula
% de la máquina destinada a la RES	45%
Rendimiento máximo	135 TFlop/s
Memoria principal	8.448 Gb
Número de nodos	44 nodos
Características de los nodos principales	Dos procesadores y 192 Gb de memoria por nodo
Tipo de CPU	Intel Gold 6148 a 2.4 GHz
Número de cores por nodo	40 cores
GFlops por core	76,8 GFlop/s
Almacenamiento de disco	1,34 Pb
Red de interconexión	InfiniBand EDR100
Sistema operativo	CentOS 7.6



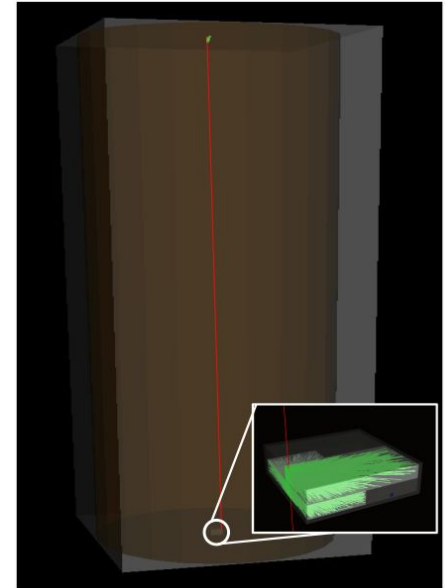
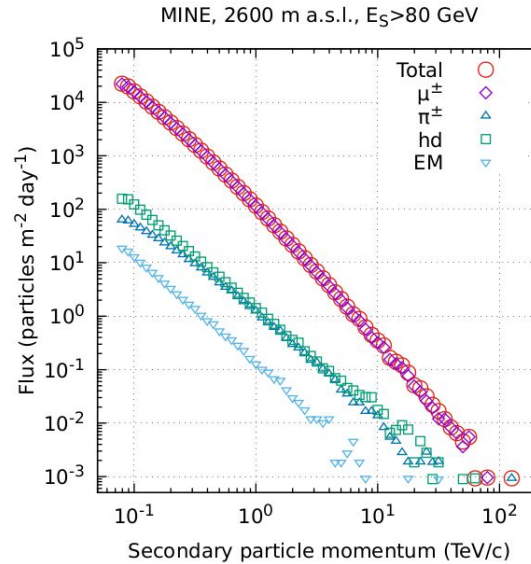
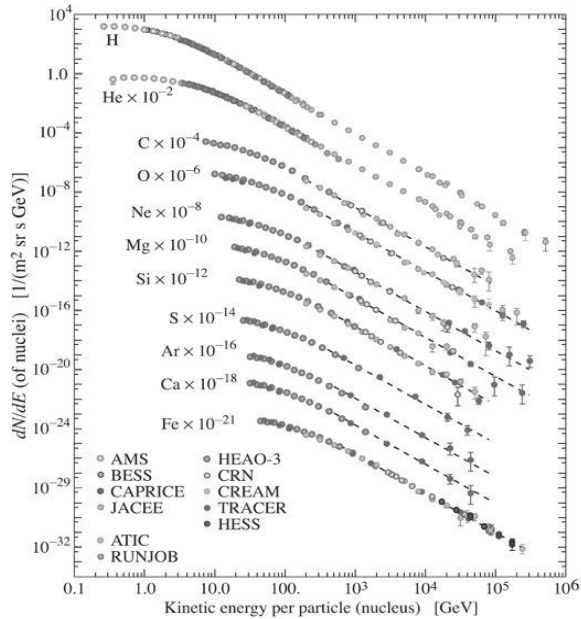
GCR Flux → Heliosphere → Modulated Flux

Modulated Flux → Magnetosphere → Primaries (S0)

Primaries (S0) → Atmosphere → Secondaries (S1)

Secondaries (S1) → Detector → Signals or Doses (S2)

Encapsulated pipelines



GCR Flux → Heliosphere → Modulated Flux

Magnetosphere

Primaries (S0)

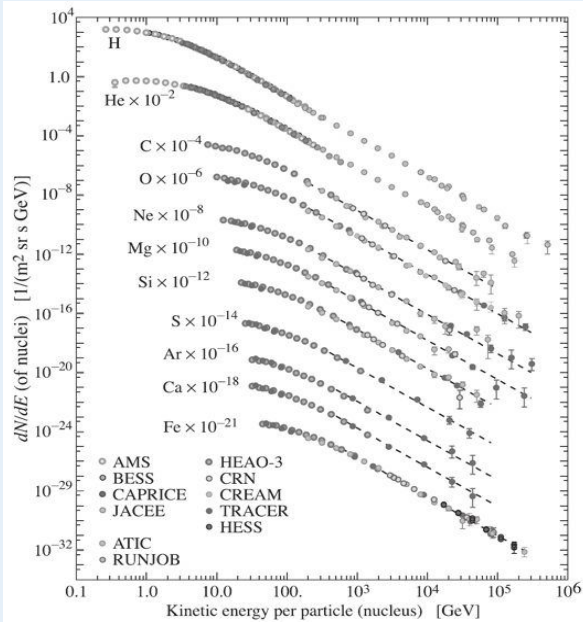
Atmosphere

Secondaries (S1)

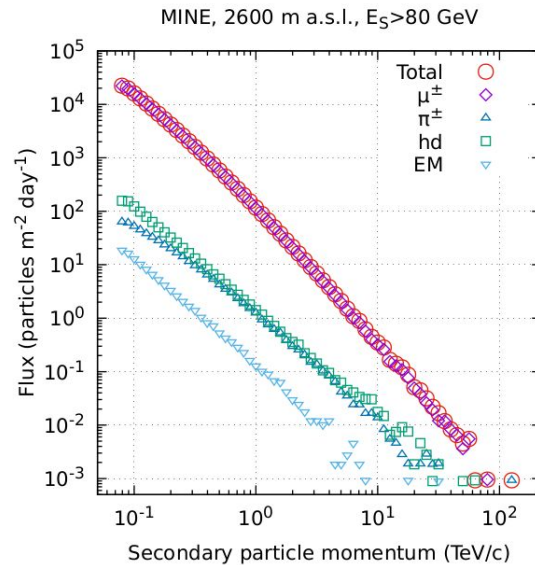
Detector

Signals or Doses (S2)

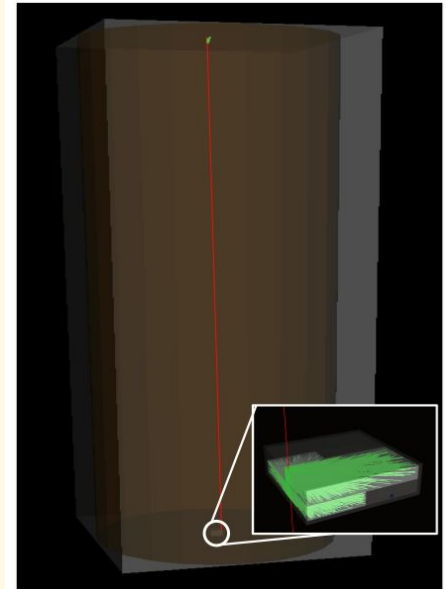
Encapsulated pipelines



onedataSim-S0



onedataSim-S1



onedataSim-S2

Astrophysical phenomena:

GRBs, Solar Activity, ...

Flux of CR

$4.5 \times 10^8 \text{ day}^{-1} \text{ m}^{-2}$

site

altitude, geomagnetic
field, atmosphere...

Time-evolving conds:

MAGNETOCOSMICS

(IGRF13&TSY),

GDAS and CORSIKA



docker

onedataSim-S0

Primaries

Encapsulated pipelines in docker images



docker

Secondaries

$4 \times 10^8 \text{ day}^{-1} \text{ m}^{-2} @4600 \text{ m asl}$

EM : MU : NE : HD= 0.875 : 0.065 : 0.050 : 0.010

onedataSim-S1

Propagation and response:
type, geometry, materials...

GEANT4 detector models



docker

Signals or Doses

onedataSim-S2

Schemas for data and metadata

Metadata:

- Language syntax: **JSON-LD 1.1 (W3C)**.

Enabling linked-data.

- Main vocabulary: **DCAT-AP2 (EC)**, a profile of DCAT2 (W3C), for government, research centers & funded projects.

- The **LAGO vocabulary**: re-profile of DCAT-AP2, extending classes & properties needed (geomagnetic locations, expected atmospheres, software...).

Data conventions compatible with DCAT-AP2:

- A super-Catalog comprises whole repository

- A Catalog is any complete simulation (S0, S1 or S2)

- A Dataset is any file belonging one simulation

```

"@context":{
  "@base":"https://mon01-tic.ciemat.es/api/v3/oneprovider/metadata/json/LAGOsim",
  "_@base":"https://hdl.handle.net/21.111998/0000-001A-6C0D-E?urlappend=",
  "@vocab":"https://github.com/SEMICEu/DCAT-AP/blob/2.0.0/releases/2.0.0/dcat-ap_2.0.0.jsonld",
  "_dcatap":"https://github.com/SEMICEu/DCAT-AP/blob/2.0.0/releases/2.0.0/dcat-ap_2.0.0.jsonld",
  "_dcatap_landing_page":"http://data.europa.eu/r5r/",
  "lago":"https://github.com/lagoproject/DMP/blob/0.0.1/schema/lagoSchema.jsonld",
  "prov":"http://www.w3.org/ns/prov#",
  "dct":"http://purl.org/dc/terms/"
},
"@id":"/sac_60_100.0_75600_QGSII_flat/DAT000703-0703-0000000144.lst.bz2",
"@type":"DataSet",
"description":"CORSIKA DAT000703-0703-0000000144.lst.bz2",
"title":"/sac_60_100.0_75600_QGSII_flat_DAT000703-0703-0000000144.lst.bz2",
"publisher":{
  "@id":"https://github.com/lagoproject/DMP/blob/0.0.1/defs/lagoCollaboration.jsonld",
  "@type":"lago:Organization"
},
"license":"https://creativecommons.org/licenses/by-nc-sa/4.0/",
"rights":"https://github.com/lagoproject/DMP/blob/0.0.1/rights/lagoCommonRights.jsonld",
"accessRights":"http://publications.europa.eu/resource/authority/access-right/RESTRICTED",
"creator":{
  "@id":"https://orcid.org/0000-0001-6497-753X",
  "@type":"lago:Person"
},
"wasGeneratedBy":"/sac_60_100.0_75600_QGSII_flat/DAT000703-0703-0000000144.lst.bz2#activity",
"distribution":"/sac_60_100.0_75600_QGSII_flat/DAT000703-0703-0000000144.lst.bz2#distribution",
"qualifiedAttribution":{
  "@id":"https://orcid.org/0000-0001-6497-753X",

```

Metadata of a S0 dataset (CORSIKA output)

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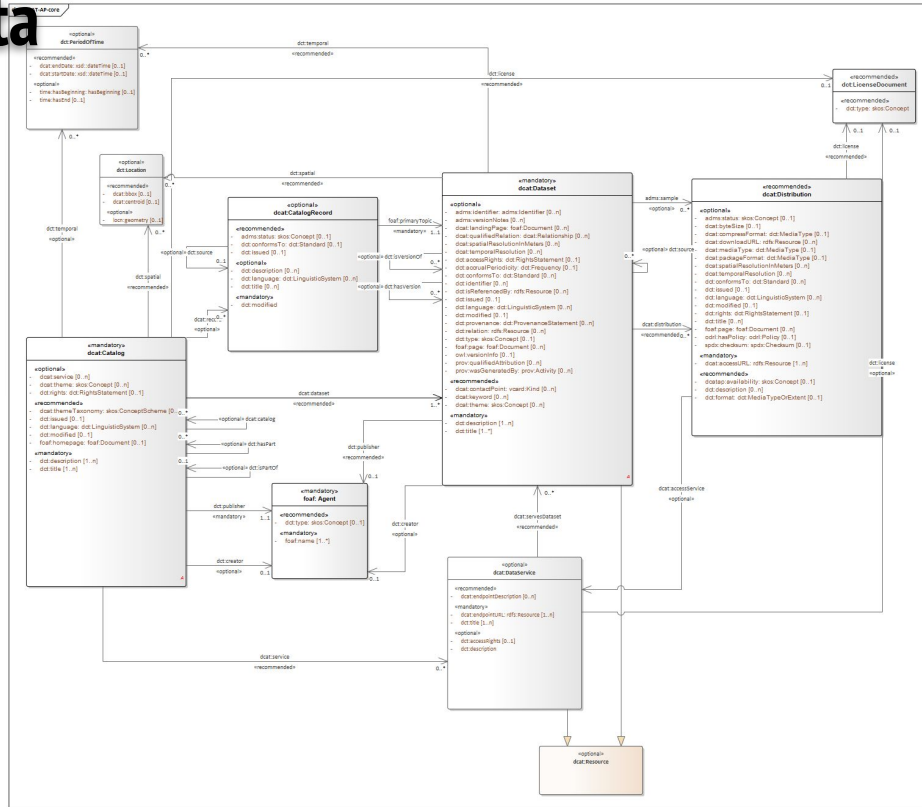
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<https://lagoproject.github.io/DMP/schema/lagoSchema/>

LAGO Data Management Plan

Home
The LAGO Data Management Plan (DMP) document
Metadata Schema ^
Metadata Schema for LAGO
Simulation Example
Definitions v
Rights v
Architecture v
HowTo's v
Contributing

This site uses [Just the Docs](#), a documentation theme for Jekyll.

lago:highEnergyCutsSecondaries
Enable high energy cuts for secondaries; 0.0 = disabled, value in GeV = enabled

@type	dc:domain	dc:range	dc:label	@default
rdf:Property owl:ObjectProperty	lago:ArtiParams	xsd:float	highEnergyCutsSecondaries	0.0

lago:corsikaParam

@type	dc:domain	dc:range	dc:label
rdf:Property owl:ObjectProperty	lago:obsLev lago:magnet lago:Atmosphere lago:Atmod lago:arrang	xsd:string	corsikaParam

lago:obsLev
Observation Level (altitude) above sea level [cm]. [xsd:double](#) type allows decimal (i.e. 2.10), non decimal (28467) and scientific notation (1633e2) values within 64-bits (double word).

@type	dc:domain	dc:range	dc:label	lago:corsikaParam
rdf:Property owl:ObjectProperty	lago:DetectorSite lago:CorsikaInput lago:ArtiParams	xsd:float	obsLev	OBSLEV

lago:magnet
Earth's mag. field (MAGNET). see values at <http://www.ngdc.noaa.gov/geomag/models/struts/calclGRFWMW> or currently at <https://www.ngdc.noaa.gov/geomag/calculators/magcalc.shtml#igrfwmm>

@type	dc:domain	dc:range	dc:label	lago:corsikaParam
rdf:Property owl:ObjectProperty	lago:DetectorSite lago:CorsikaInput	lago:MagnetComponents	magnet	MAGNET

Definitions in the LAGO DMP

Schemas for data and metadata

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View provided by  ceta-ciemat-01 

 LAGOsims 

 S0_and_5184000_645000.0_77402_QGSII_volu_HEcuts_defaults

 S0_and_60_77402_QGSII_flat_defaults

 S0_and_7776000_400000.0_77402_QGSII_volu_HEcuts_defaults

 S0_and_86400_470000.0_77402_QGSII_volu_defaults

 S0_and_86400_520000.0_77402_QGSII_volu_defaults

 S0_and_86400_570000.0_77402_QGSII_volu_defaults

 S0_and_86400_620000.0_77402_QGSII_volu_defaults

 S0_and_86400_77402_QGSII_flat_defaults

Partial content of LAGOsims repo

**Every Catalog
(simulation)
has a
Handle.net PiD**



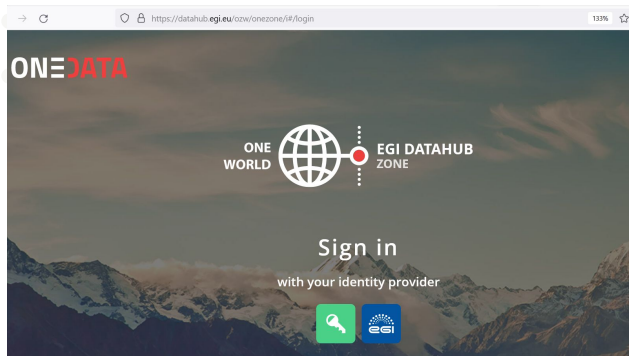
Where are the meta & data stored?

ONE DATA is an object-based distributed FS focused on cloud and HPC:

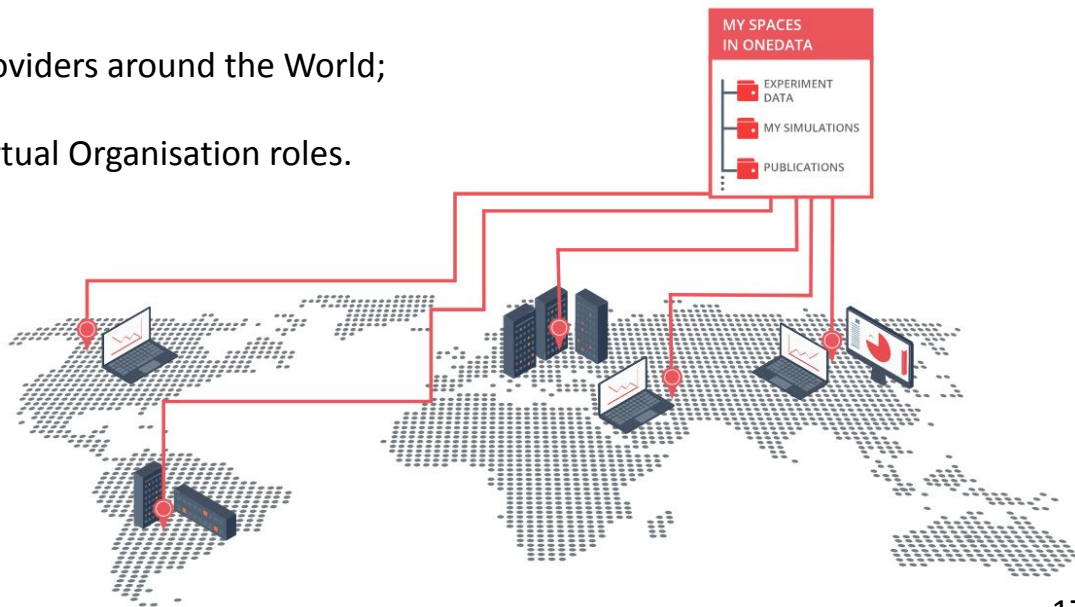
- offers unified data access and roles across globally distributed environments;
- manages metadata and expose them to harvesters.

EGI/EOSC supports the “DataHub” instance that:

- allows extending the capacity by adding providers around the World;
- asks for (Handle.net) PiDs;
- enable pan-European IdPs and translate Virtual Organisation roles.



<https://datahub.egi.eu>



How are the meta & data stored and retrieved?



OneData providers can be far away from the computing nodes

Remote Data and Metadata access:

- POSIX VFS
- CDMI API
- REST API

Simulations are:

- CPU & disk (scratch) intensives.
- Multi-threaded

We are only interested in

- getting remote inputs
- storing final results
- pipelining the copies
- manage metadata



HPC facilities

Desktops



Nodes on public clouds

How are the meta & data stored and retrieved?

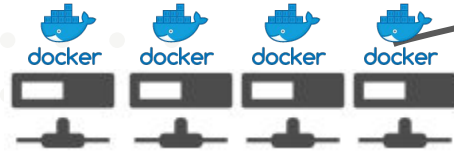


Remote Data and Metadata access:

- POSIX VFS
- CDMI API
- REST API

onedataSim images:

- guarantee the compatibility across platforms
- packet the communication with the OneData APIs



HPC facilities

Desktops



Nodes on public clouds

How are the meta & data stored and retrieved?

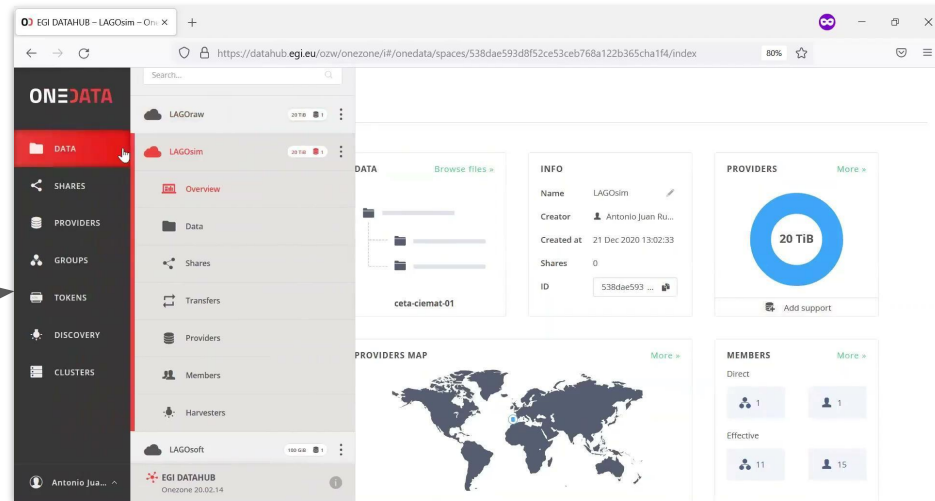


LAGO members can:

- explore whole repository with a Web browser;
- download non-owned data after embargo;
- authenticate through LAGO IdPs;
- maintain their account, roles and permissions stored by the eduTEAMS platform (GEANT).



Desktops



OneData Web portal

How are the meta & data gathered and accessed?

ONE DATA



OAI-PMH API

GUIDELINES - COMMUNITIES FACETED SEARCH ABOUT -

/ Datasets / S1_and_10_115.0_77402_QGSII ...

Social: Google+, Twitter, Facebook

Dataset: S1_and_10_115.0_77402_QGSII_flat_defaults

Test description in Dublin Core

Identifier	
PID	http://hdl.handle.net/21.12145/VN6EYkc
Source	https://datahub.eui.eu/share/c54dacd50d25a229cc660ed69252947fch27f0
Metadata Access	http://datahub.eui.eu/oai_pmh?verb=GetRecord&metadataPrefix=oai_dc&identifier=oai:datahub.eui.eu:27e4fb48f8a40087527cc39169d63963cha225

Provenance	
Creator	A. J. Rubio-Montero, https://orcid.org/0000-0001-6497-753X
Instrument	LAGO Observatory
Publisher	LAGO Collaboration

Metadata gathered for a simulation

Handle.net PiD to friendly Web page and alternate links through CDMI & REST

Mendeley Data

EOSSC

77 results

Filter Results:

- Document (39)
- Other (137)
- Interactive Resource (9)
- Dataset (27)
- Video (2)
- Image (2)
- Software/Code (2)
- Table Data (4)
- File Set (4)
- Text (2)

SOURCE TYPES:

- Data Repositories (2)

SOURCES:

- Zenodo (9)
- Mendeley Data (4)
- EOSC - IT Center for Science (1)
- Signum Academic Research System (1)
- The Australian Social Science Data Archive (1)
- Active (1)

EOSC Pillar "National Initiatives" Survey (SUF edition)
 Budde, Anita, Höttinger, Lisa, Kazimirk, Lars, Beckmann, Volker, Bröten, Vincent et al
 Published: 1 January 2019. The Australian Social Science Data Archive
 Full edition for scientific use. The EOSC Pillar "National Initiatives" Survey is a cross-section study in Austria, Belgium, France, Germany, and Italy. The survey aims at landscaping national initiatives of open research data and services with relevance to the European Open Science Cloud (EOSC). Four target groups are part of the study - with structures, research infrastructures, universities and funding bodies. The survey contains questions on the perception of EOSC, as well as detailed questions assessing e.g. the e-infrastructure's business models, technical characteristics, access conditions, faithfulness of the data holdings and adopted policies related to open science.

Annex 3 dataset: Survey for Academic Assessment Systems for Open Science & Research Data (anonymous)
 Kovacs, Elina, Mordjaki, Henriikka, Pöörten, Janna, Gregory, Kathleen, haanola, Dragon et al
 Published: 20 April 2021 (Zenodo)
 The survey served as a reference for the project members to overview current state-of-the-art and identify gaps in responsible academic assessment of research and researchers throughout Europe. This dataset is an appendix to Annex 3 of EOSC Co-creation report "Making FAIR Assessments Possible" (https://doi.org/10.5281/zenodo.493375). This report is a deliverable of EOSC Co-creation projects ("European overview of career assessment systems" and "Vision for research data in research careers", funded by the EOSC Co-Creation funding). Further information on these projects can be found here: https://awit.mendeley.com/network/eosc-co-creation.

Annex 4 dataset: OS-CAM Case Studies

882K datasets interlinked with publications



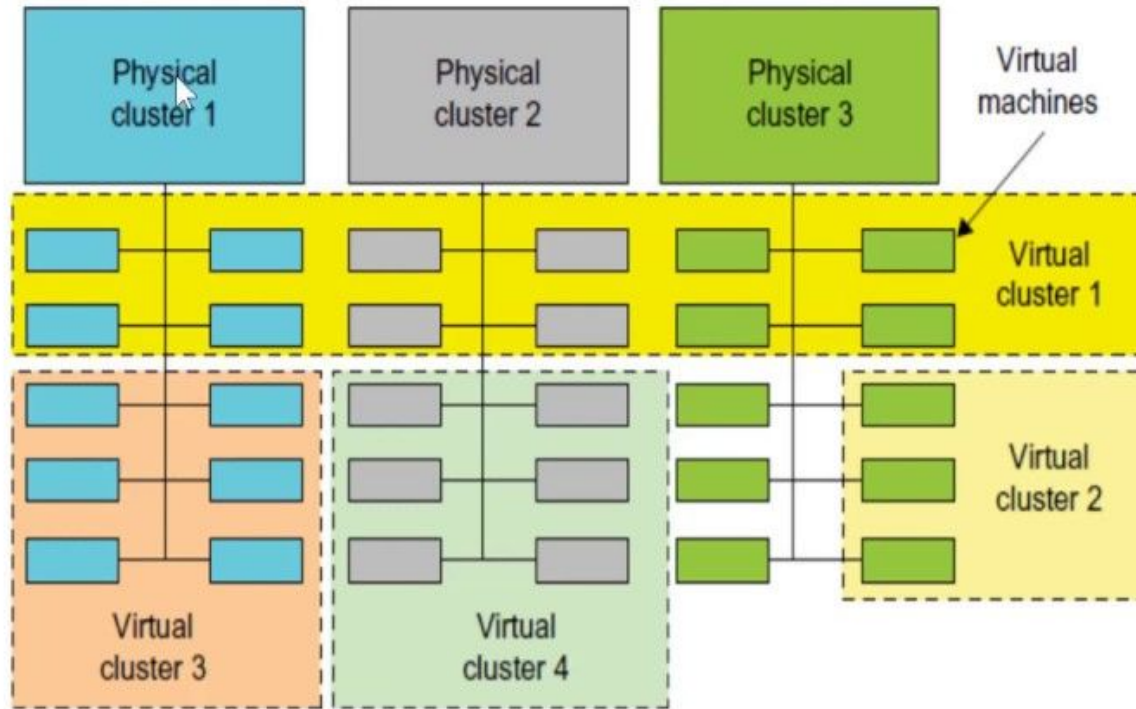
Search data

eg: IPCC

Search engine

Public harvesters

cluster virtualization



A cloud platform with four virtual clusters over three physical clusters shaded differently.

Infrastructure manager

IM Dashboard

<https://appsgrycap.i3m.upv.es:31443/im-dashboard/login>

Infrastructure Manager
Dashboard.



Login with EGI Check-in →

Available Topologies



If you need a new topology please contact us [✉](#)

About



Check-in

Choose your academic/social account

GÉANT eduTEAMS Service

<https://moodle.learn.eosc-synergy.eu/course/view.php?id=16>

google it: “moodle eosc lago course”

or



Choose Your Identity Provider



Google

idhub-local.eduteams.org

1. Find your Identity Provider



Search by institution name, email to find your Home Organization, Institution or University.

2. Log-in



Use your institutional credentials to log in as you normally do. If you do not have any, use any of the available guest and social identity

3. Enjoy



Access the content and features provided to your community.

4. Explore



Continue to work seamlessly with your community access.

Search...

Start a virtual machine with extra HD



VM

Launch a OSCAR Virtual Cluster



Launch an Elastic OSCAR Virtual Cluster



SLURM virtual cluster



Launch a Kubernetes Virtual Cluster



kubernetes

Launch an Elastic Kubernetes Virtual Cluster

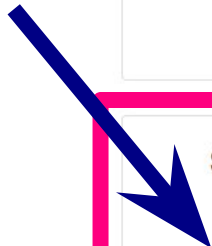


kubernetes











Docker VMs

Launch a Storm Virtual Cluster



Launch an InfluxDB on top of a Kubernetes Virtual Cluster



Cloud Credentials

ID	Type	Info
BIFI	 	Host: https://colossus.cesa VO: lagoproject.net
CESGA	 	Host: https://fedcloud-osse VO: lagoproject.net
CETA-CIEMAT	 	Host: https://controller.ceta VO: lagoproject.net
IFCA	 	Host: https://api.cloud.ifca. VO: lagoproject.net
NCG	 	Host: https://stratus.ncg.in VO: lagoproject.net

Credential ✕

asoreyh@gmail.com

Select VO:

lagoproject.net ▾

Select provider:

CETA-GRID ▾

Cancel
Add

+ New Credential

 **EC2**

 Google Cloud

 Microsoft Azure

 Open Nebula

 openstack.

 linode

 kubernetes

 Infrastructure Manager

You need to enroll yourself at the LAGO VO

Creating a new v-cluster at cloud

SLURM virtual cluster

Description: TOSCA for launching a SLURM Virtual Cluster.

Infrastructure Name
ceta04.p7

FE Node Features WNs Features Cloud Provider Selection

Cloud Provider:

Select Cloud Provider:
CETA-CIEMAT


Select only one of this options AppDB or Site image:
Select AppDB image:
- Select one image -

Select Site image:
Image for EGI Docker [Ubuntu/18.04/VirtualBox]

Submit Cancel

Site Resource Usage:

VCPUs RAM (GB) Instances Float IPs SGs



Resource	Usage Percentage
VCPUs	~75%
RAM (GB)	~75%
Instances	~25%
Float IPs	~25%
SGs	~25%

Creating a new v-cluster at cloud

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FE Node Features | WNs Features | **Cloud Provider Selection**

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Select Cloud Provider:
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Image for EGI Docker [Ubuntu/18.04/VirtualBox]

Site Resource Usage:

- VCPUs
- RAM (GB)
- Instances
- Float IPs
- SGs

Submit Cancel

Creating a new v-cluster at cloud

SLURM virtual cluster

Description: TOSCA for launching a SLURM Virtual Cluster.

Infrastructure Name

[FE Node Features](#) [WNs Features](#) [Cloud Provider Selection](#)

Number of WNs in the cluster

Number of CPUs for the WNs

Amount of Memory for the WNs

Size of the disk to be attached to the WN instances (Set 0 if disk is not needed)

Path to mount the WN attached disk

Creating a new v-cluster at cloud

SLURM virtual cluster

Description: TOSCA for launching a SLURM Virtual Cluster.

Infrastructure Name
ceta04.p7

FE Node Features [WAs Features](#) [Cloud Provider Selection](#)

Number of CPUs for the front-end node
1

Amount of Memory for the front-end node
1 GB

Size of the disk to be attached to the FE instance (Set 0 if disk is not needed)
0 GB

Or URL of the disk to be attached to the FE instance (format: ost://api.cloud.ifca.es/<vol_id>

Path to mount the FE attached disk
/home/data

Creating a new v-cluster at cloud

SLURM virtual cluster

Description: TOSCA for launching a SLURM Virtual Cluster.

Infrastructure Name
ceta04.p7

FE Node Features [WNs Features](#) [Cloud Provider Selection](#)

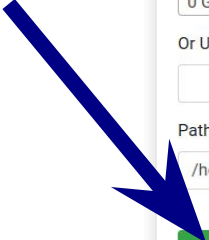
Number of CPUs for the front-end node
1

Amount of Memory for the front-end node
1 GB

Size of the disk to be attached to the FE instance (Set 0 if disk is not needed)
0 GB

Or URL of the disk to be attached to the FE instance (format: ost://api.cloud.ifca.es/<vol_id>)

Path to mount the FE attached disk
/home/data



Creating a new v-cluster at cloud

SLURM virtual cluster



Current LAGO services at cloud (v-clusters) (+ RES' HPC)

The screenshot shows the EGI IM Dashboard with the following elements:

- Header: EGI logo, IM Dashboard, Infrastructures, Advanced, External Links, and user profile (Hernán Asorey).
- Section: My Infrastructures with Refresh and New deployment buttons.
- Table with columns: Name, Infrastructure uuid, Cloud Type, Cloud Info, Status, VMs, and Actions.
- Table content:

Name	Infrastructure uuid	Cloud Type	Cloud Info	Status	VMs	Actions
Fermi	7951b9f4-4091-11ef-bf01-8a1b936d600f	EGI	Site: CETA-GRID VO: lagoproject.net	configured	0	Outputs
Voyager	7dafc6e2-4070-11ef-826f-8a1b936d600f	EGI	Site: CETA-GRID VO: lagoproject.net	configured	0, 1, 2, 3, 4, 5, 6, 7, 8	Outputs
Stargazer	5c0ba8ee-406b-11ef-a7ac-eacfa880e500	EGI	Site: CETA-GRID VO: lagoproject.net	configured	0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10	Outputs

Additional annotations on the Voyager and Stargazer rows:

- Voyager:** 1 FE + 8 v-nodes: 4 CPUs, 32GB RAM, 200 HDD
- Stargazer:** 1 FE + 10 vnodes: 8 CPUs, 64GB RAM, 200 HDD

Footer: Showing 1 to 3 of 3 entries, page 1 of 1.

+ Single virtual machines on-demand

+ 20TB cloud storage via Onedata

How does it work?



HPC provider assigns cloud resources to EOSC:
 n Nodes, r GB/TB of RAM, d TB local storage

FAIR: catalogs are findable, accessible, interoperable, and reusable



docker containers with our codes are deployed from docker HUB in the virtual cluster



virtual cluster

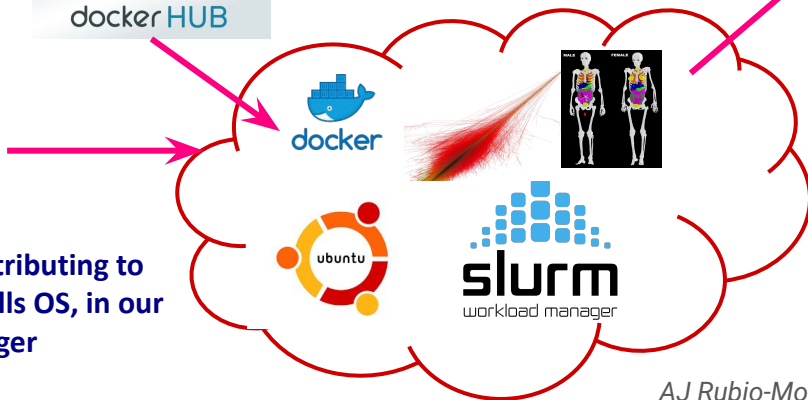
Results are stored at cloud-based storage services. Access through personal tokens



PID (Persistent Identifiers) are assigned for each data catalog



Infrastructure Manager



web-based service with templates for distributing to available resources in virtual clusters. Installs OS, in our case, ubuntu 20.04 + slurm manager

OneDataSim



All resour... ▾



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TARGET USERS

- Students
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- Research Communities
- Research Projects
- Research Groups



OneDataSim

A tool to simulate the radiation expected by the interaction of Astroparticles with the atmosphere at any place in the World: an implementation of LAGO ARTI for EOSC.

Organisation: [Latin American Giant Observatory](#)

☆☆☆☆☆ (0.0 /5) 0 reviews Add to comparison Add to favourites

Access the resource

ORDER REQUIRED

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ABOUT

DETAILS

REVIEWS (0)

OneDataSim is the implementation of LAGO-ARTI for cloud-based high performance computing environments, looking for the standardisation of the simulations and data analysis in LAGO, and allowing the curation, re-usage and publishing of the results, following the FAIR principles according to the LAGO Data Management Plant.

As cosmic rays interact with the atmosphere, they produce cascades with up to 10^{12} secondary particles denominated Extensive Air Showers (EAS). A huge amount of computational resources are needed to simulate and analyse the complete development of the cascades. For doing this we developed LAGO-ARTI, an own designed framework including different simulations tools and own codes to determine in a very precise way, the signals expected at any detector of any type, in any particular site around the World, and under realistic atmospheric and geomagnetic time-evolving conditions.

LAGO, the Latin American Giant Observatory, is an extended cosmic ray observatory, consisting of a wide network of water Cherenkov detectors located in 10 countries. With different altitudes and geomagnetic rigidity cutoffs, their geographic distribution, combined with the new electronics for control, atmospheric sensing and data acquisition, allows the realization of diverse astrophysics studies at a regional scale. LAGO is mainly oriented to perform basic research focusing on three main areas: high energy phenomena, the measurement of atmospheric radiation at ground level and space weather and climate monitoring.

SCIENTIFIC CATEGORISATION



- Natural Sciences
- Physical Sciences

CATEGORISATION

- Software
- Software Package
- Data

Free service now publicly available at [EOSC Marketplace](#)

one \$TOKEN to rule them all



LAGO OneDataDim

☰ README.md



LAGO onedataSim : packed tools for ARTI simulation and analysis on OneData

Plain tests in dev branch: build passing

Build tests for building onedatasim-s0 image: build passing

Build tests for building onedatasim-s1 image: build failing

Description

LAGO onedataSim packages all requirements for running ARTI into a Docker container, giving researcher the advantage of obtaining results on any platform that supports Docker (Linux, Windows and MacOs on personal computers, HTC/HPC clusters or cloud public/private providers).

However, the main objective of onedataSim is to standardise the simulation and its analysis in LAGO Collaboration in order to curate, re-use and publish the results, following the Data Management Plan (DPM) established. For this purpose, onedataSim includes two main programs:

1. `do_sims_onedata.py` that:

<https://github.com/lagoproject/onedataSim>

LAGO docker hub



The screenshot shows the Docker Hub interface for the repository `lagocollaboration/onedatasim-s0`. The page is in dark mode. At the top, there's a navigation bar with the Docker Hub logo, search, help, and user icons, and "Sign In" and "Sign up" buttons. Below the navigation bar, the repository name is displayed along with "Explore" and "lagocollaboration/onedatasim-s0". The repository icon is a 3D cube. The repository name `lagocollaboration/onedatasim-s0` is prominently displayed, followed by "By lagocollaboration · Updated about 2 years ago". There are links for "IMAGE", "0 stars", and "350 downloads". The "Tags" tab is selected, showing a list of tags. The "latest" tag is highlighted, with a "Copy" button next to the command `docker pull lagocollaboration/onedatasim-s0:latest`. Below this, a table lists the tags with columns for "Digest", "OS/ARCH", and "Compressed Size". The "dev" tag is also visible below the "latest" tag.

Explore / lagocollaboration/onedatasim-s0


 **lagocollaboration/onedatasim-s0**
By lagocollaboration · Updated about 2 years ago

IMAGE
☆0 ↓ 350

Overview **Tags**

Sort by Newest ▾ Filter Tags

TAG

[latest](#) `docker pull lagocollaboration/onedatasim-s0:latest` Copy

Last pushed 2 years ago by lagocollaboration

Digest	OS/ARCH	Compressed Size
bbc4efb46f32	linux/amd64	925.89 MB

TAG

[dev](#) `docker pull lagocollaboration/onedatasim-s0:dev` Copy

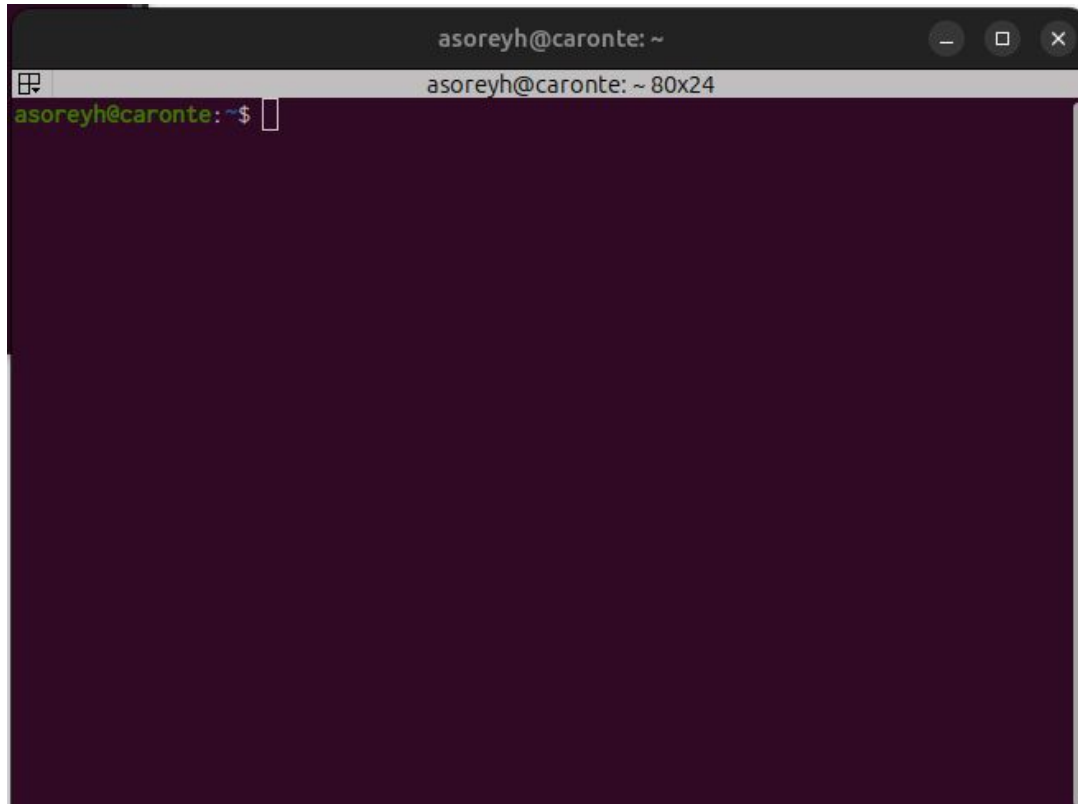
Last pushed 2 years ago by lagocollaboration

Digest	OS/ARCH	Compressed Size
f039e38fe7b1	linux/amd64	925.53 MB

lagocollaboration/onedatasim-s0

- CentOS Linux release v 7.8.2003 (Core, rpm based)
- Standard installation of LAGO CORSIKA (CORSIKA v 7.7402 compiled with LAGO standards)
- ARTI v 1.9.0
- onedataSim 1.0 branch: dev commit: dc803020
- FUSE v 2.9
- oneclient v 20.02.17
- coreutils, vim, rsync, screen, python v 3.6.8, ...

let's go to the terminal

A screenshot of a terminal window. The window title bar shows "asoreyh@caronte: ~" and standard window control buttons. The terminal content shows the prompt "asoreyh@caronte: ~\$" followed by a cursor. The terminal background is dark purple.

```
asoreyh@caronte: ~$
```

TOKEN & PROVIDER

The access to the shared resources is granted through OAuth2 TOKEN provided at EGI DATAHUB: <https://datahub.egi.eu/>

```
export TOKEN="MDAxY2xv...b5Ao"
```

The provider allows the access to the cloud storage server:

```
export ONEPROVIDER="ceta-ciemat-01.datahub.egi.eu"
```

Dockers

Get the docker

```
docker rmi lagocollaboration/onedatasim-s0:dev
```

```
docker pull lagocollaboration/onedatasim-s0:dev
```

Run the docker

```
docker run \  
  --privileged \  
  -e ONECLIENT_ACCESS_TOKEN=$TOKEN \  
  -e ONECLIENT_PROVIDER_HOST=$ONEPROVIDER \  
  -it lagocollaboration/onedatasim-s0:dev \  
  bash
```

EXTRACT FROM



The *Meiga* framework
Simulations tool for astroparticle physics

A. Taboada Núñez^{1*}, C. Sarmiento-Cano²
¹ITeDA-CNEA-CONICET
²UIS

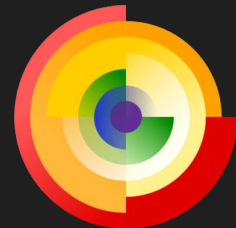
XIII LAGO WORKSHOP
21-26 February 2022
Tucumán, Argentina

*alvaro.taboada@iteda.cnea.gov.ar

AND FROM



```
1 G4Course *MyNewCourse::Construct() {
2
3     G4Course *course = new G4Course();
4     course→title("Geant4 for Beginners. A crash course");
5     course→author("Hernán Asorey");
6     course→email("asoreyh@gmail.com");
7     course→description("a hands-on Geant4 crash course");
8     course→school("La Conga Physics");
9     course→site("github.com/asoreyh/geant4-course");
10    course→year(2023);
11    course→duration(4*h);
12    course→license("CC0 1.0 Universal");
13    return course;
14 }
```





geant4

```
1 // A toolkit for the simulation of the  
2 passage of particles through matter.
```

```
3  
4 // Its areas of application include high energy, nuclear and  
5 accelerator physics, as well as studies in medical and space  
6 science
```

```
7  
8  
9 G4Download("geant4.web.cern.ch/");
```

```
10 G4Docs("geant4.web.cern.ch/docs/");
```

```
11 G4AppDocs("geant4-userdoc.web.cern.ch/UsersGuides/ForApplicationDe  
12 veloper/BackupVersions/V10.7/html/index.html");
```

```
13 G4Examples("Check the #{geant4_examples}/ dir for extra fun");
```

```
14 // IMPORTANT NOTICE
```

```
// I will not spend time showing how to install G4 (and root) →
```




G4 install (by [@asoreyh](#))

```
1
2
3 # While Geant4 have multiple dependencies,
4 some of them are required and some others are
5 needed for optional features.
6
7 # Check the official installation guide at
8 https://geant4-userdoc.web.cern.ch/UsersGuides/InstallationGuide/html
9
10 # I prepared a bash script for installing the required dependencies,
11 root and geant4 at ${HOME}/work. (Ubuntu 23.04)
12 # Warning 1: it will change your .bashrc file.
13 # Warning 2: it will take time (up to several hours).
14
15 $ curl -Lo install-root-geant4.sh
16 https://www.dropbox.com/s/ej67f1hc88u7w1a/install-root-geant4.sh?dl=1
17 $ chmod 744 install-root-geant4.sh
18 $ ./install-root-geant4.sh
```



G4 docker

(by [@asoreyh](#))



```
1 # Docker is a platform designed to help devs  
2 build, share, and run modern apps. We handle the  
3 tedious setup, so you can focus on the code.
```

```
4  
5 # I prepared two Dockerfiles for this course. Follow the instructions  
6 and download them from (look for them at the utils directory):
```

```
7  
8 $ git clone https://github.com/asoreyh/geant4-course.git
```

```
9  
10 # Otherwise, you can pull the docker image from my docker hub:
```

```
11  
12 $ docker pull asoreyh/root:latest # root version 6.28.04 (2023)
```

```
13 $ docker pull asoreyh/geant4:latest # G4 version 10.07.04 (2022)
```

```
14  
# Blank installation. Check the docs!
```

```
# There is also a virtual machine built by the Geant4 collaboration
```



G4 docker

(by [@asoreyh](#))



```
1
2
3 # Important note: You will need to follow these
4 steps and provide privileged access to this
5 docker to be able to run the QT Geant4
6 visualization from docker.
7
```

```
8 # open a terminal and enable local access to xhost:
```

```
9
10 $ xhost +local:root
```

```
11 # and run the docker (if you don't download the docker images it will
12 download them):
```

```
13
14 $ docker run --privileged -it -e DISPLAY=$DISPLAY -v
/tmp/.X11-unix:/tmp/.X11-unix asoreyh/geant4:10.07.04
```



geant4

```
1
2
3
4 // A comment about versions.
5 /*
6    By the end of 2022 a new major release, G4 11
7    was released (current 11.2.2)
8
9
10   In this course we will use the latest G4 10,
11   G4 10.7.4
12 */
13
14
```



[G4Help\(\);](#)

Geant4 philosophy → Toolkit

No main code, tools for building your own app



Toolkit

Actions



Components (interfaces) of your app

The building blocks of your app

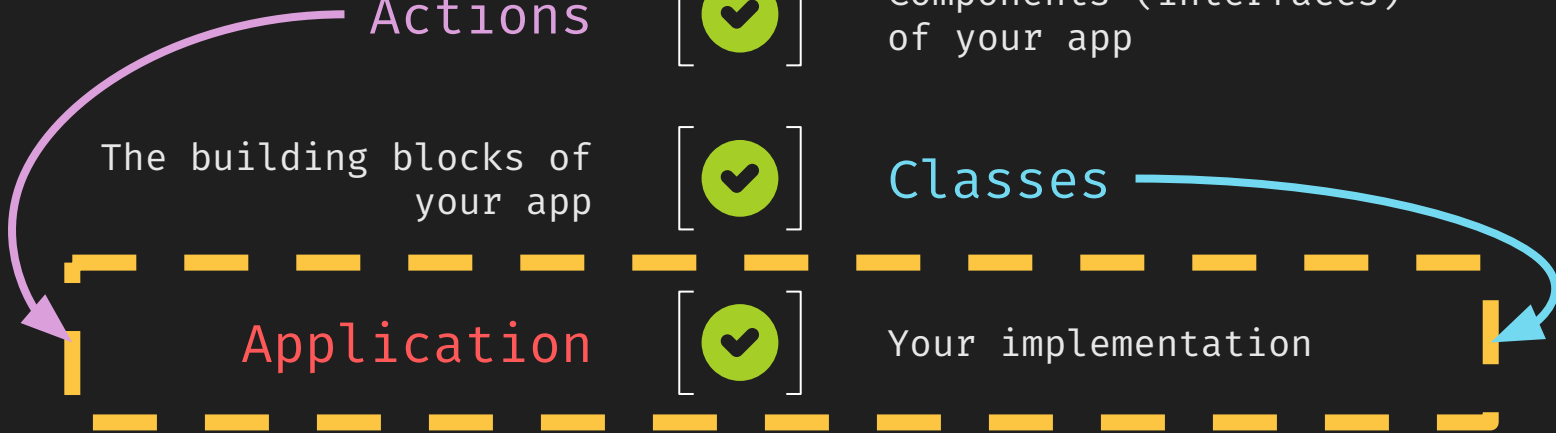


Classes

Application



Your implementation



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G4RunManager()

```
1
2  /*
3     This object is the “heart” of any G4 application. It is always mandatory and
4     should be defined in your main app.cc code (dose.cc in our example)
5
6     It controls the “flow” of the run
7
8     All the interfaces (G4 toolkit) are defined and provided here:
9
10    * G4VUserDetectorConstruction           ← geometry construction
11
12    * G4VUserPhysicsList                   ← all your physics is here
13
14    * G4VUserActionInitialization         ← actions
15
16        * G4VUserPrimaryGeneratorAction   ← primary particles production
17
18        * G4UserRunAction                   ← optionals...
19
20        * G4UserSteppingAction, ...
21
22    * UIManager, VisManager, ...
23
24 */
```





First step: the main code (dose.cc)

```
1 // 0. I/O operations
2 #include <iostream>
3 // 1. G4RunManager class
4 #include "G4RunManager.hh"
5 // 2. User interface
6 #include "G4UIExecutive.hh"
7 #include "G4VisExecutive.hh"
8 // 3. Visualization manager
9 #include "G4VUserDetectorConstruction.hh"
10 #include "G4UImanager.hh"
11 #include "G4VUserDetectorConstruction.hh"
12 #include "G4UImanager.hh"
13 int main()
14 {
15     //3. visualization manager
16     G4VisManager *visManager = new G4VisExecutive ();
17     visManager->Initialize ();
18     // 4. start the session - and compile to see what happens
19     ui->SessionStart ();
20     return 0;
21 }
```

Before to continue we need to define our “volumes”, i.e., where your app detectors and volumes will exist and what are they made of? (always 3 volumes, see next)

Create your G4VUserDetectorConstruction
(and register it at your runManager)

// Clearly we are still not ready for **initialize()** the **runManager** as we need to continue defining our **building blocks**



[100%] Built target dose
asoreyh@caronte:~/Dropbox/projects/geant4/geant4-course/codes/src/build\$./dose

Aborted (core dumped)
asoreyh@caronte:~/Dropbox/projects/geant4/geant4-course/codes/src/build\$./dose



And the new dose.cc

```
1 // 0. I/O operations
2 #include <iostream>
3 // 1. G4RunManager class
4 #include "G4RunManager.hh"
5 // 2. User interface
6 #include "G4UImanager.hh"
7 #include "G4UIExecutive.hh"
8 // 3. Visualization
9 #include "G4VisManager"
10 #include "G4VisExecuti
11 // once the detector d
12 #include "construction
13 int main(G4int argc, ch
14 //1. create the G4F
15 G4RunManager *runMa
16 // once detector is
17 // but we are still
18 runManager->SetUser
19 //5. Initialize the
20 // runManager->Init
21 //2. create the use
22 G4UIExecutive *ui = ne
23 G4UImanager *UIManager = G4UImanager::GetUIpointer();
24 //3. visualization manager
25 G4VisManager *visManager = new G4VisExecutive();
26 visManager->Initialize();
27 // 4. start the session - and compile to see what happens
28 ui->SessionStart();
29 return 0;
30 }
```

It compiles! :)

Before to continue we need to define our “physics”, i.e., what kind of physics our app will implement?

Create your G4VUserPhysicsList
(and register it at your runManager)

```
...t4-course/codes/src/build$ make
...dose.cc.o
...course/codes/src/dose.cc: In function
...variable]
...r::GetUIpointer());
...construction.cc.o
```

ork... :/

Physics, this is why we are here...



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```
// Physics process
```

Physics processes describe how particles interact with materials.

- electromagnetic
- hadronic
- transportation
- decay
- optical
- photolepton_hadron
- Parameterisation

```
G4PhysicsListDocs("https://geant4-userdoc.web.cern.ch/UsersGuides/ForApplicationDeveloper/BackupVersions/V10.7/html/TrackingAndPhysics/physicsProcess.html");
```



And the new lines at dose.cc

It compiles! :)

```

1 // [...]
2 // once the physics list is ready, include it
3 #include "physics.hh"
4
5 int main(G4int argc, char** argv) {
6
7 // [...]
8 // once the physics list is ready, include it
9 runManager->SetPhysicsListFactory(new PhysicsListFactory());
10 // [...]
11 // after the physics list is ready, create the user actions
12 UImanager->ApplyActionInitialization();
13 UImanager->ApplyPrimaryGeneratorInitialization();
14 // ... draw the geometry
15 UImanager->ApplyActionInitialization();
16 // [...]
17 }

```

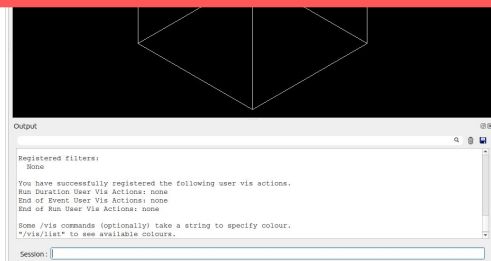
```

asoreyh@caronte:~/Dropbox/projects/geant4/geant4-course/codes/src/build$ make
[ 33%] Building CXX object CMakeFiles/dose.dir/dose.cc.o
/home/asoreyh/Dropbox/projects/geant4/geant4-course/codes/src/dose.cc: In function 'int main(int, char**)':
dose.cc:26:18:
...
build$ ./dose
...

```

Ok, we have volumes, materials and physics...
 We are almost ready → we need actions!

**Create your G4VUserActionInitialization
 and G4VUserPrimaryGeneratorAction**
 (and register them at your runManager)



Actions, let's the things evolve



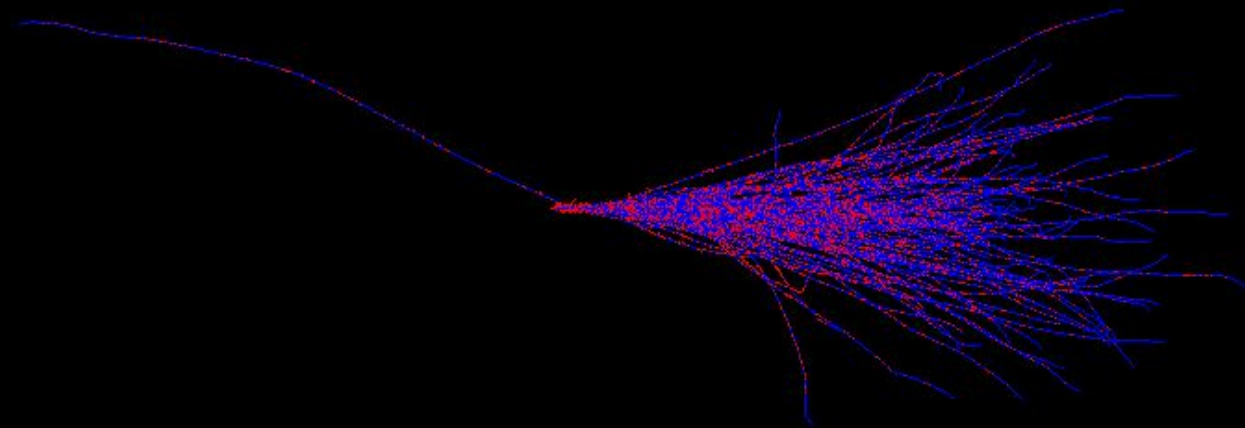
```
1 // We need two interfaces
```

- 2
- 3 • **G4VUserActionInitialization** is an interface to create and register the
- 4 **G4VUserPrimaryGeneratorAction** (mandatory) and other user actions
- 5 ◦ Build() ← function
- 6
- 7 • **G4VUserPrimaryGeneratorAction** is an interface (action!) to describe how the
- 8 primary particles (injection) should be produced
- 9 ◦ GenerateParticles() ← function
- 10 ◦ Typically, but not always → **G4ParticleGun**
- 11 ◦
- 12
- 13
- 14



and “that’s it”

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[G4Help\(\);](#)

Geant4 philosophy → the problem

No main code, tools for building your own app



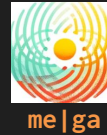
Toolkit



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Meiga, the sorceress

developed by A. Taboada-Núñez et al.



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[Download Meiga from GitHub](#)

MEIGA: modular matter-radiation interaction simulations

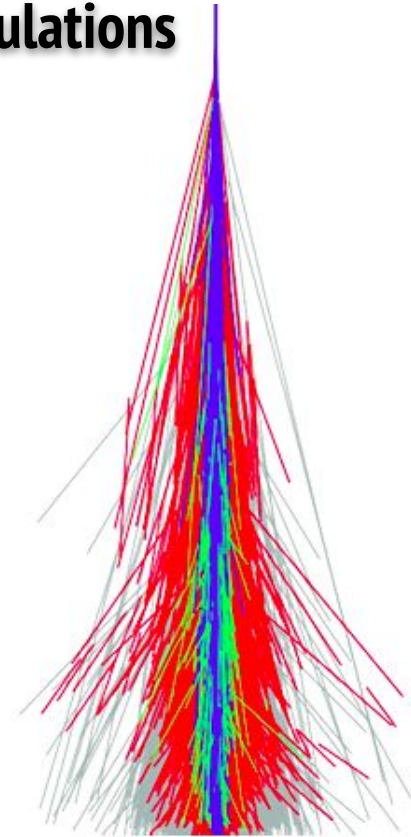
- What is it?

***Meiga** is a collection of C++ classes that integrate the cosmic-ray flux calculation, particle propagation and the detector response in dedicated applications.*

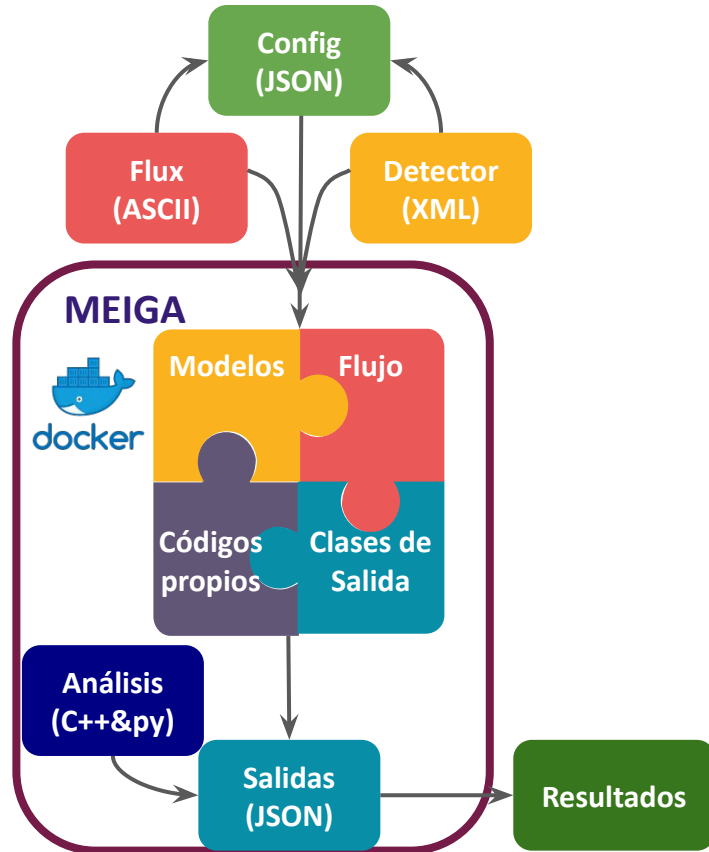
- How?

The framework is supported by an structure of classes and methods which provide the necessary interfaces between the user and the detector description.

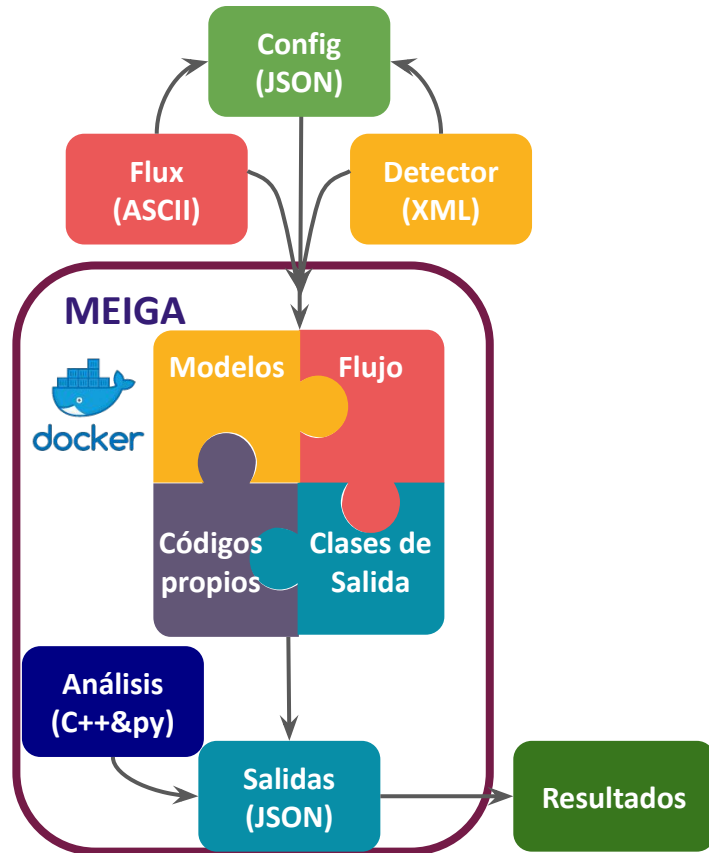
The applications are written in such a way that users can run different simulation setups by means of configuration files.



MEIGA: modular matter-radiation interaction simulations



MEIGA: modular matter-radiation interaction simulations



after install root, Geant4 and Meiga dependences, download meiga from GitHub and follow the typical installation sequence:

```
$ git clone git@github.com:ataboadanunez/meiga.git
```

```
$ cd meiga
```

```
$ mkdir build install
```

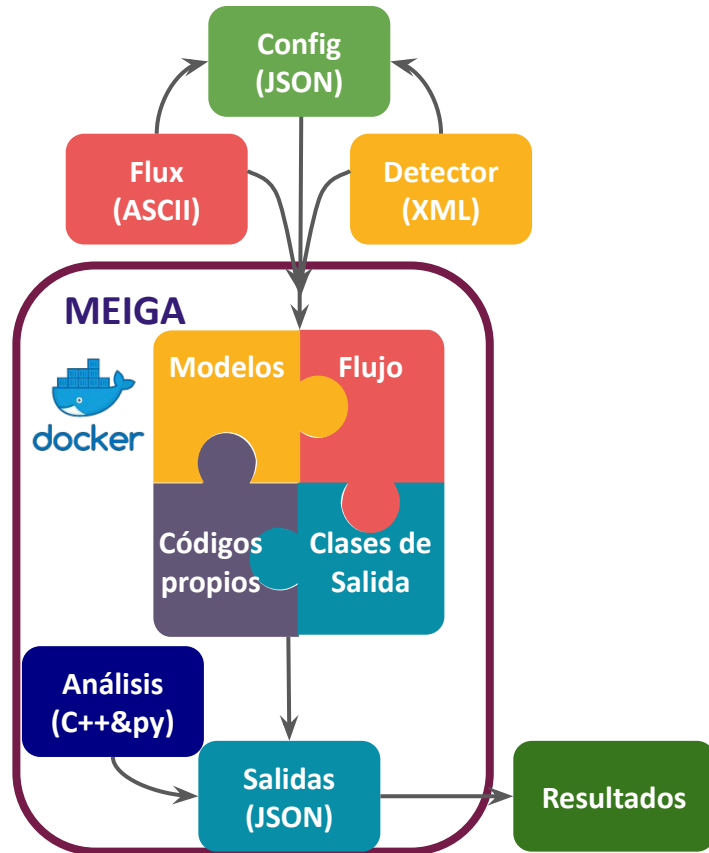
```
$ cd build
```

```
$ cmake -DCMAKE_INSTALL_PREFIX=../install ../src
```

```
$ make -j 4; make -j 4
```

```
$ make install
```

MEIGA: modular matter-radiation interaction simulations



or, use docker (all running dependencies included)

```
$ docker pull asoreyh/meiga:dev
```

of course, you need docker properly installed in your system



asoreyh/meiga:dev

- Ubuntu 22.04.03 LTS
- At /opt dir you will find:
 - root **6.28.06**, from `$ docker pull asoreyh/root:6.28.06`
 - geant4 **10.7.4**, from `$ docker pull asoreyh/geant4:10.7.4`
 - Meiga **2.1.1-dev** commit **39b950**
 - MEGAcmd 1.6.3.2 (for cloud interactions using mega.io CLI)
- coreutils, vim, rsync, screen, python v 3.10.12, ...



asoreyh/meiga:dev

- Ubuntu 22.04.03 LTS
- At /opt dir you will find:
 - root **6.28.06**, from `$ docker pull asoreyh/root:6.28.06`
 - geant4 **10.7.4**, from `$ docker pull asoreyh/geant4:10.7.4`
 - Meiga **2.1.1-dev** commit **39b950**
 - MEGAcmd 1.6.3.2 (for cloud interactions using mega.io CLI)
- coreutils, vim, rsync, screen, python v 3.10.12, ...

but it will be updated soon...

- Meiga 3 (G4-11 compatible)

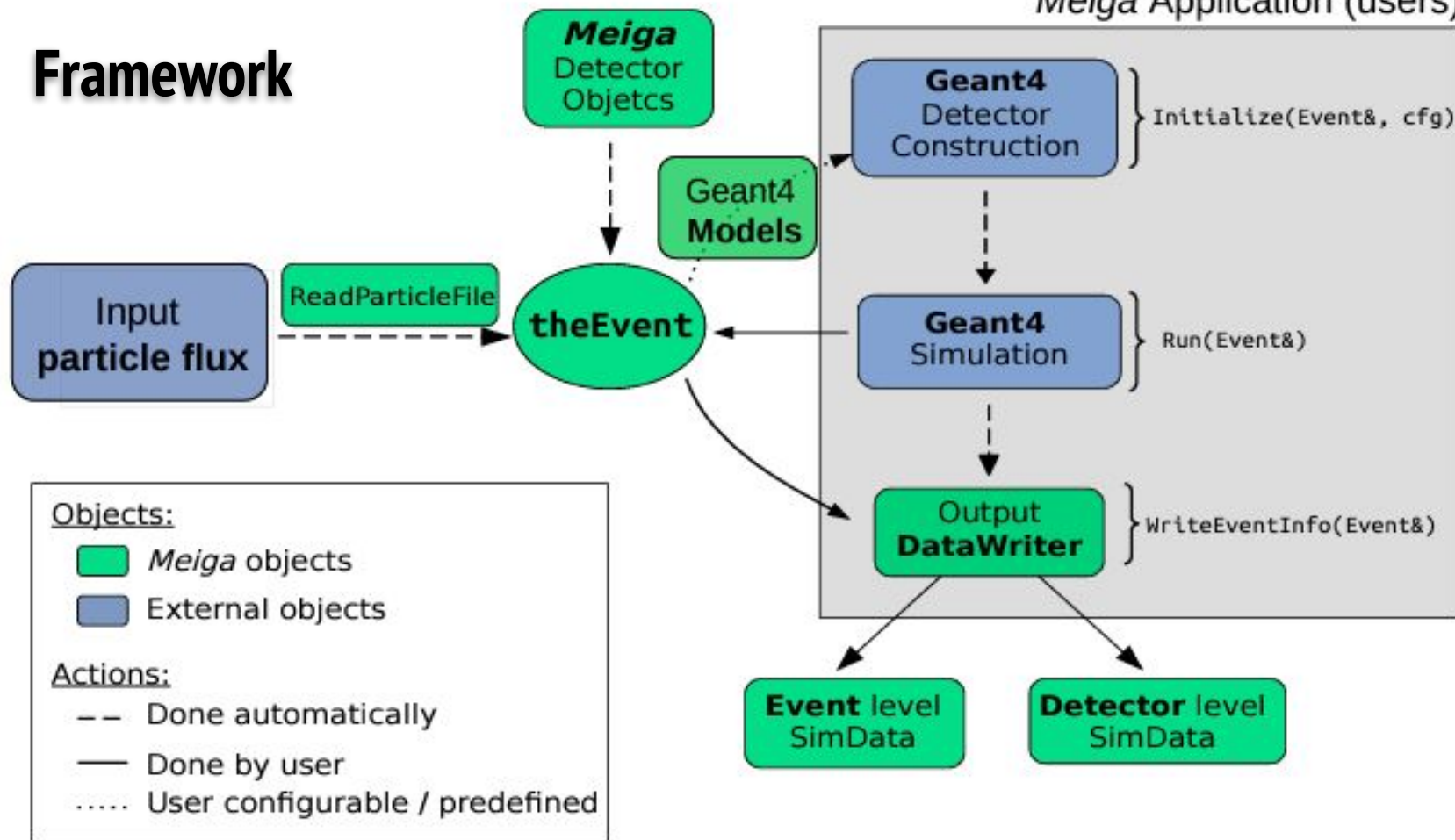
- Meiga 2 (G4-10 compatible)

+ numpy, + pandas, + tools

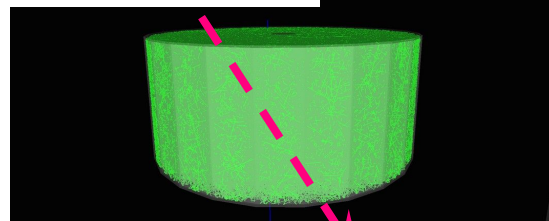
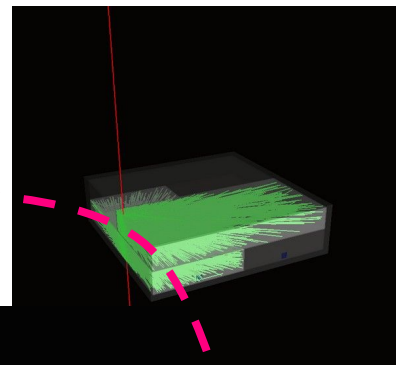
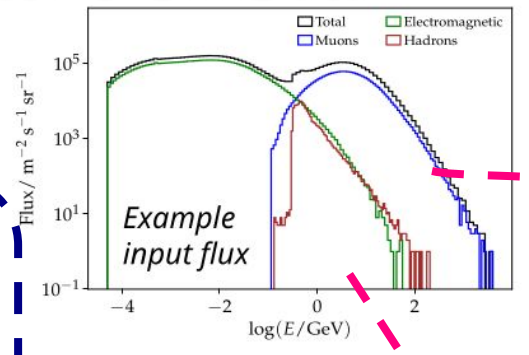
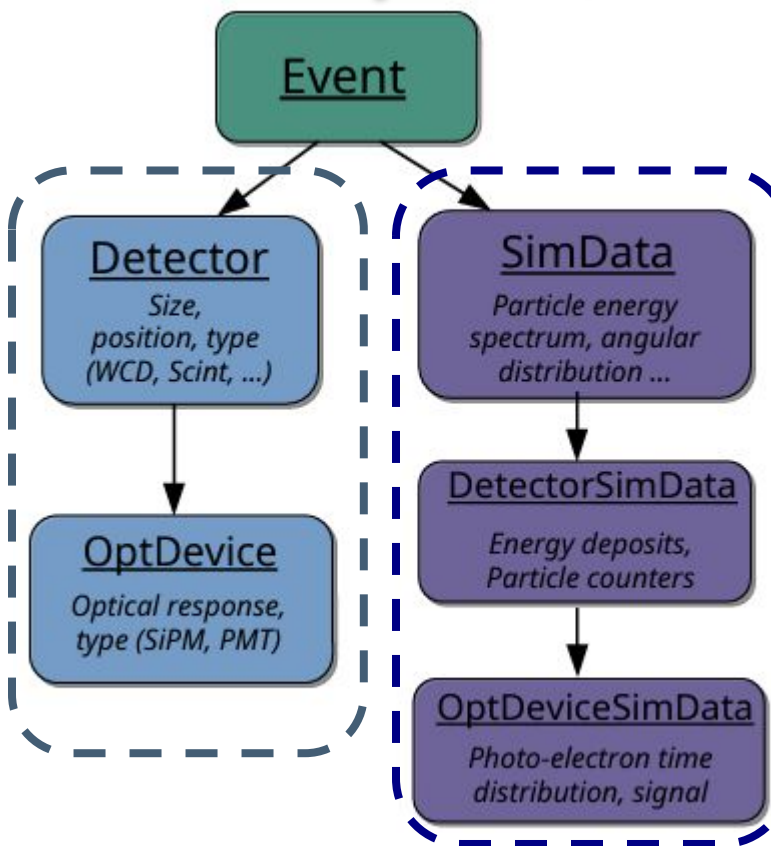


Framework

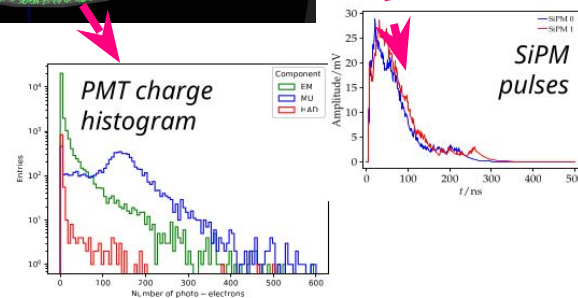
Meiga Application (users)



Hierarchy: Event, Detector & SimData



Meiga is supported on a **hierarchical structure** to handle the **detector description** and to access **simulation data** at different levels



Applications

Three methods in the *main()* function to manage information at the *Event* object level

```
int main (int arg, char** argv) {  
    (...)  
    // initialize the Event object  
    Event theEvent;  
    // create Application class object  
    fG4ExSimulator = new G4ExSimulator();  
    // set the simulation up using using the configuration file  
    fG4ExSimulator->Initialize(theEvent, fCfgFile);  
    // run Geant4 simulation  
    fG4ExSimulator->RunSimulation(theEvent);  
    // write output data  
    fG4ExSimulator->WriteEventInfo(theEvent);  
    (...)  
    return 0;  
}
```

Check the examples in the Applications directory

Initialize

Read the config.json file and sets the simulation within this application

```
G4ExSimulator::Initialize(Event& theEvent, string fileName) {  
    // JSON parser from boost  
    boost::ptree root;  
    boost::ptree::read_json(fileName, root);  
    // get the particle flux  
    fInputFile = root.get<string>("InputFile");  
    // read the DetectorList.xml  
    fDetectorList = root.get<string>("DetectorList");  
    (...)  
    // Fills the Event from with the particle flux  
    theEvent = ReadParticleFile::EventFileReader(fInputFile);  
    // Fills the the Detector Configuration in the Event  
    ConfigManager::ReadDetectorList(fDetectorList, theEvent);  
}
```

RunSimulation

1. Checks for particles

```
SimData& simData = theEvent.GetSimData();  
if (!simData.GetTotalNumberOfParticles())  
    return false;
```

2. Construct and sets the Geant4 RunManager

```
auto fRunManager = G4RunManagerFactory::CreateRunManager();  
// Initialize the DetectorConstruction class  
auto fDetectorConstruction = new G4ExDetectorConstruction(theEvent);  
fRunManager->SetUserInitialization(fDetectorConstruction);  
// Initialize the PhysicsList  
fRunManager->SetUserInitialization(fPhysicsList);  
// Initialize PrimaryGenerator Action  
auto fPrimaryGenerator = new G4ExPrimaryGeneratorAction(theEvent);  
fRunManager->SetUserInitialization(fPrimaryGenerator);
```

3. Loop over particles list or particle beams

```
for (auto it = simData.GetParticleVector().begin(); it != simData.GetParticleVector().end();  
++it) {  
    G4ExSimulator::CurrentParticle = *it; // Allows access to primary particle during  
simulation process  
    fRunManager->BeamOn(1);  
}
```


Actions

G4Actions is where the user can access data from G4 simulation. To store information in the Meiga classes, just ensure the constructor of the G4Action class takes the Event object as an argument.

```
// get the pmt object by its ID
auto& pmt = fEvent.GetDetector(detId).GetOptDevice(pmtId);
// check if Cherenkov photon is detected using its energy and the PMT QE
if (!pmt.IsPhotonDetected(energy))
    return continue;
// if we arrive here, photon is detected. Get PMT SimData
auto& pmtSimData = fEvent.GetDetectorSimData(detId).GetOptDeviceSimData(pmtId);
// save photon time
pmtSimData.AddPETimeDistribution(time);
```

Time distribution of photo-electrons in a PMT, from meiga/src/G4Models/G4MPMTAction.cc

WriteEventInfo

1. Retrieve simData from the Event

```
// for accessing Simulated Data at Detector/Event level  
SimData& simData = theEvent.GetSimData();
```

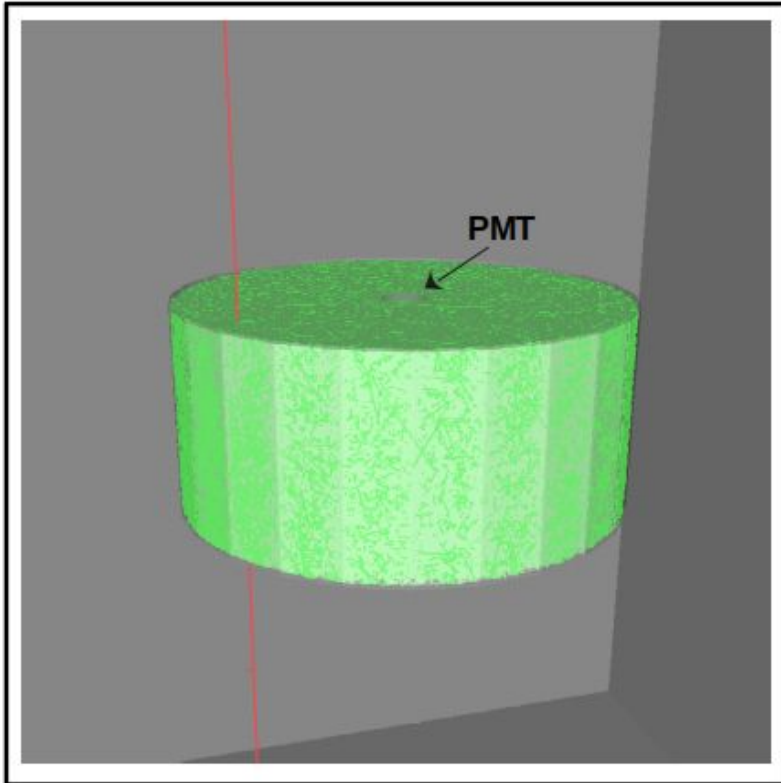
2. Loops over Detectors and get DetectorSimData

```
// access using the detector ID  
for (auto detIt = theEvent.DetectorRange().begin(); ... detIt++) {  
    int detId = detIt->second.GetId();  
    DetectorSimData& detSimData = simData.GetDetectorSimData(detId);  
}
```

3. Gets the PMT SimData for that particular detector

```
OptDeviceSimData& odSimData = detSimData.GetOptDeviceSimData(odId);  
  
// get the photo-electron time distribution  
const auto *peTimeDistribution = odSimData.PETimeDistribution();  
  
// and the number of PE  
size_t npe = *(peTimeDistribution)->size()
```

G4WCDSimulator : the LAGO detector simulation



A typical LAGO WCD detector

- cylindrical water container of configurable r radius and h height
- material: PEHD of configurable t thickness
- Internal coating: Tyvek
- Hamamatsu R5912 8" PMT, including QE
- Tap water optic characteristics
- Cherenkov production and tracking
- PE production, timing and accounting

The DetectorList.xml

```
<?xml version='1.0' encoding='ISO-8859-1'?>
```

```
<detectorList>
```

```
  <injectionMode type="eCircle">
    <x unit="m"> 0 </x>
    <y unit="m"> 0 </y>
    <z unit="m"> 0 </z>
    <radius unit="m"> 1.5 </radius>
    <height unit="m"> 2 </height>
  </injectionMode>
```

eCircle: particles are injected in a circle of radius <radius> and at height <height>.

eHalfSphere: particles are injected over a semi-sphere of radius <radius> and origin <x>, <y>, <z>.

eVertical: particles are injected vertically at a fixed position (given by <x>, <y>, <z>).

eFromFile: injection coordinates are taken from the input file.

```
  <detector id="0" type="eWCD">
    <x unit="cm"> 0.0 </x>
    <y unit="cm"> 0.0 </y>
    <z unit="cm"> 0.0 </z>
    <tankRadius unit="cm"> 98 </tankRadius>
    <tankHeight unit="cm"> 120 </tankHeight>
    <tankThickness unit="mm"> 10 </tankThickness>
  </detector>
</detectorList>
```

WCD id "0" of radius <tankRadius> and height <tankHeight> and thickness <tankThickness> located at position <x>, <y> and <z>.

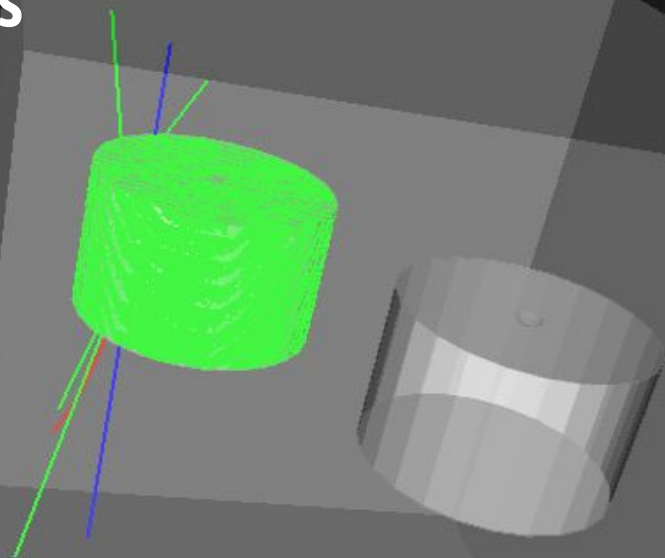
Default are used if no magnitude is given.

Defaults can be changed in the DetectorProperties.xml file

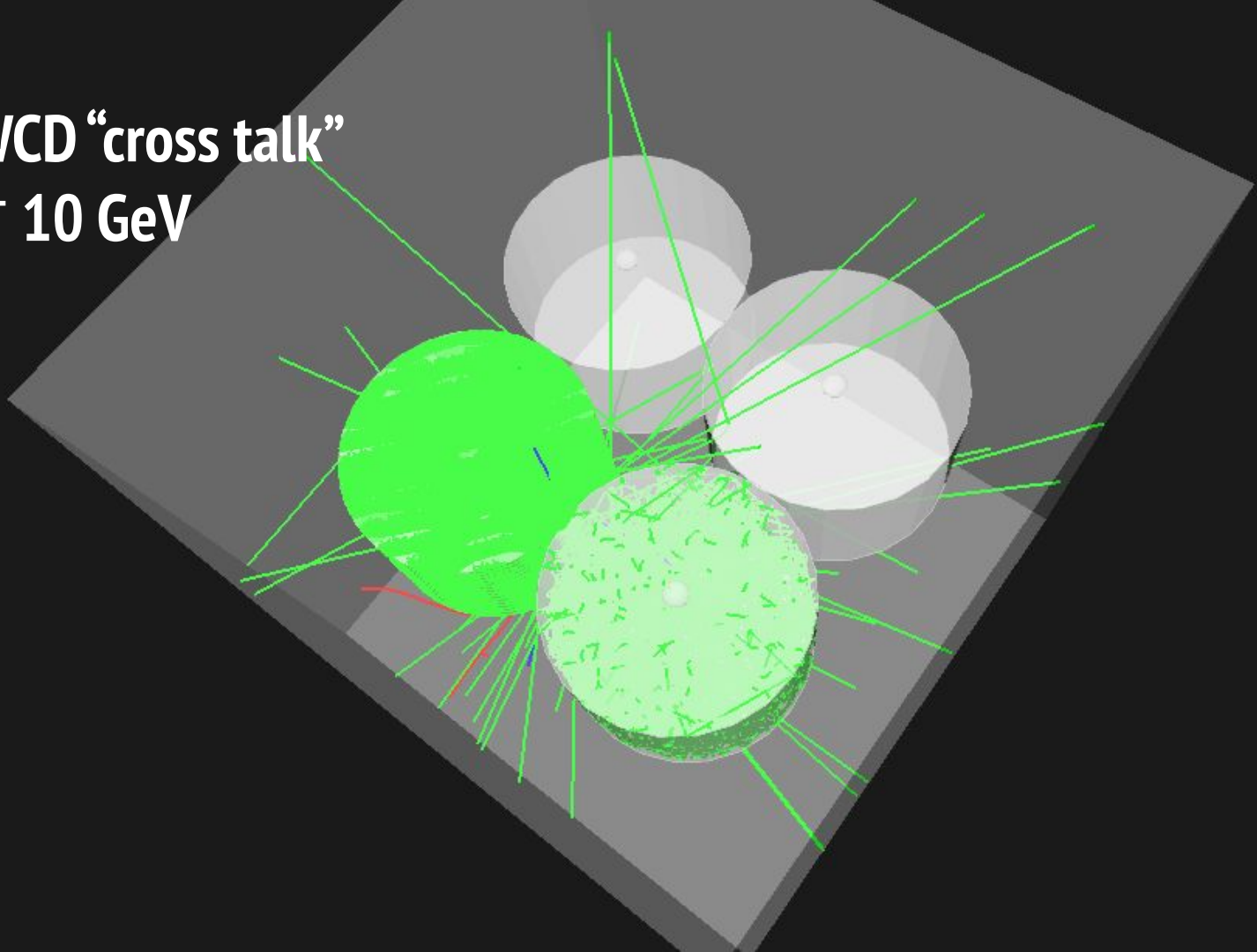
repeat this block for each detector in an array.

id should be alphanumeric but unique

Multiple detectors



WCD "cross talk"
 $e^- 10 \text{ GeV}$



The config.json - input

```
"Input" :  
{  
    "Mode" : "UseARTI",  
    "InputFileName" : "../../../src/Documentation/SampleFlux/vertical_muon.txt"  
},
```

Mode: can be UseARTI or UseEcoMug for selecting between the two input types

InputFileName: path to input file in case UseARTI is chosen.

InputNParticles: number of muons to be injected in case UseEcoMug is chosen.

If UseARTI is chosen, InputFileName should be an ASCII 12-col ARTI-like:

```
CorsikaId px py pz x y z shower_id prm_id prm_energy prm_theta prm_phi
```

e.g. for a vertical muon+ with p=1 GeV/c in the -z direction (position will depend on injection mode)

```
5 0 0 1 0 0 0 0 0 0 0 0
```


The config.json - output

```
"Output" :  
{  
    "OutputFile" : "./output.json",  
    "CompressOutput" : true,  
    "SaveInput" : true,  
    "SavePETimeDistribution" : false,  
    "SaveEnergy" : true,  
    "SaveCharge" : true  
},
```

OutputFile: path to the output file.

CompressOutput: enable compression of output file (.gz).

SavePETimeDistribution: save photo-electron time distributions for each injected particle.

SaveComponentsPETimeDistribution: save photo-electron time distributions by particle component (electromagnetic, muons, hadrons).

SaveEnergy: save energy deposits in the detector.

SaveCounts: save particle counters (for scintillator bars).

SaveComponentsEnergy: save energy deposits in the detector by particle component.

The config.json - Detectors

```
"DetectorList" : "./DetectorList.xml",  
"DetectorProperties" : "./DetectorProperties.xml",
```

DetectorList: path to the detector list file.

DetectorProperties: path to file with the default detector properties.

The config.json - Simulation

```
"Simulation" :  
{  
    "SimulationMode" : "eFast",  
    "GeoVisOn" : false,  
    "TrajVisOn" : false,  
    "CheckOverlaps" : false,  
    "Verbosity" : 1,  
    "RenderFile" : "VRML2FILE",  
    "PhysicsName" : "QGSP_BERT_HP"  
}
```

SimulationMode: eFull by default. Some applications allow eFast for fast simulation
GeoVisOn and **TrajVisOn:** if True, a render file with geometry (and particle trajectories) of the detector is generated.

CheckOverlaps: if True detects overlaps between detector volumes.

Verbosity: level of Geant4 verbosity output. Warning, >1 could produce large outputs

RenderFile: type of render file. For now, only .wrl files are allowed.

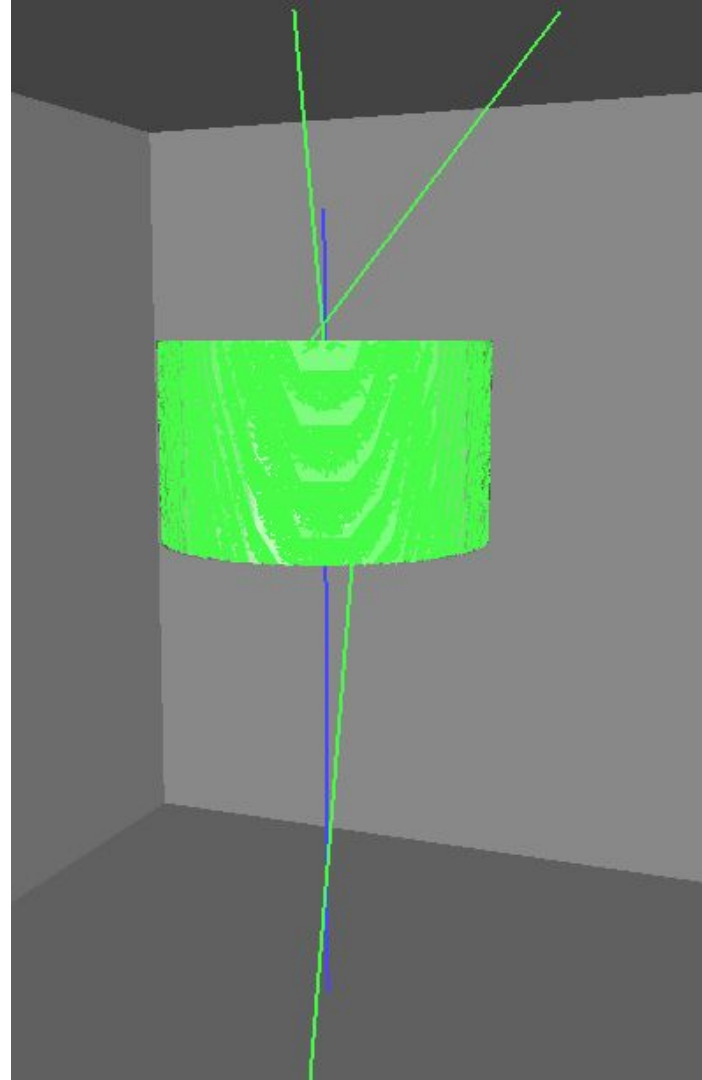
PhysicsName: name of the physics list.

VEM (Vertical Equivalent Muon)

Vertical (and central) Equivalent Muon

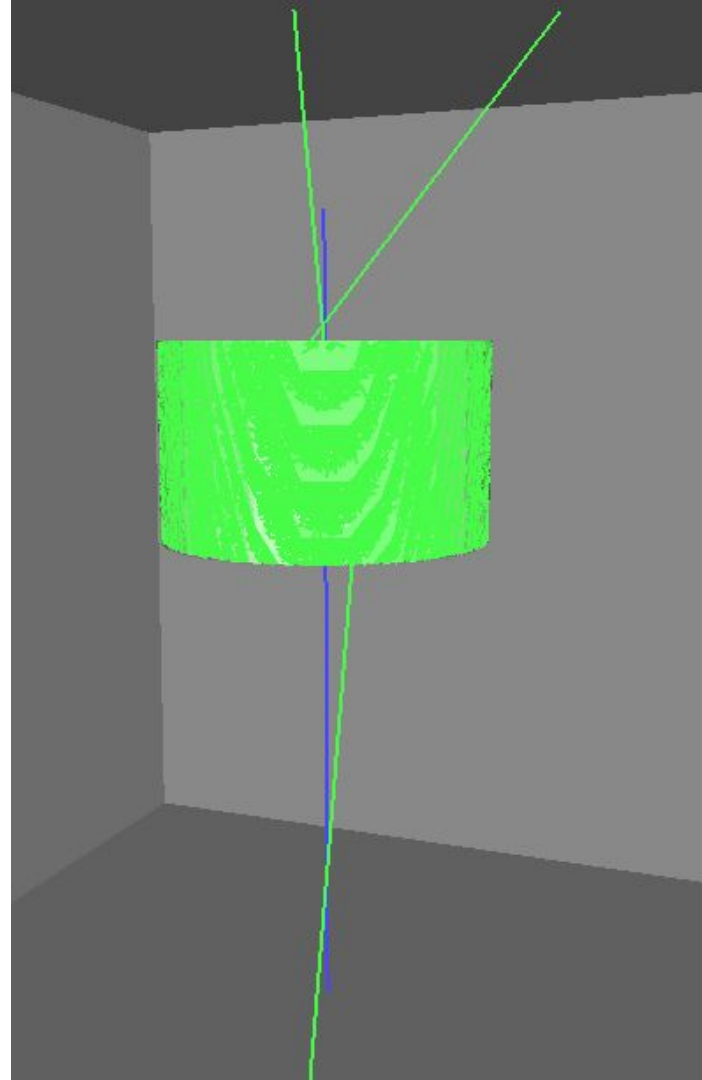
Calibration magnitude:

1 VEM = $\langle \text{td} \rangle$ photoelectrons = $(2 \cdot h)$ MeV



The output.json(.gz)

```
{
  "Output": {
    "Event_0": {
      "InputFlux": {
        "ID": -13,
        "Position": [0.0, 0.0, 2000.0],
        "Momentum": [0.0, 0.0, -5000.0]
      },
      "Detector_0": {
        "EnergyDeposit": 199.62353614726368,
        "OptDevice_0": {
          "Charge": 670
        }
      }
    }
  },
  "DetectorList": {
    "Detector_0": {
      "ID": 0,
      "Name": "eWCD",
      "Position": [0.0, 0.0, 0.0],
      "OptDeviceList": [0]
    }
  }
}
```



Let's do it together

warning: docker images only include defaults

```
$ docker run -it asoreyh/meiga:dev bash
# cd /opt/meiga/build/Applications/G4WCDSimulator
# ll
```

```
total 1052
```

```
drwxr-xr-x 3 root root 4096 Nov 12 2023 ./
drwxr-xr-x 8 root root 4096 Nov 12 2023 ../
drwxr-xr-x 3 root root 4096 Nov 12 2023 CMakeFiles/
-rw-r--r-- 1 root root 383 Nov 12 2023 DetectorList.xml
-rwxr-xr-x 1 root root 1033392 Nov 12 2023 G4WCDSimulator*
-rw-r--r-- 1 root root 557 Nov 12 2023 G4WCDSimulator.json
-rw-r--r-- 1 root root 15349 Nov 12 2023 Makefile
-rw-r--r-- 1 root root 2273 Nov 12 2023 cmake_install.cmake
```

Our main files

edit the DetectorList.xml

```
<?xml version='1.0' encoding='ISO-8859-1'?>
```

```
<detectorList>
```

```
  <injectionMode type="eVertical">
```

```
    <x unit="m"> 0 </x>
```

```
    <y unit="m"> 0 </y>
```

```
    <z unit="m"> 2 </z>
```

```
    <radius unit="m"> 1.5 </radius>
```

```
    <height unit="m"> 2 </height>
```

```
  </injectionMode>
```

```
  <detector id="0" type="eWCD">
```

```
    <x unit="cm"> 0.0 </x>
```

```
    <y unit="cm"> 0.0 </y>
```

```
    <z unit="cm"> 0.0 </z>
```

```
    <tankRadius unit="cm"> 98 </tankRadius>
```

```
    <tankHeight unit="cm"> 120 </tankHeight>
```

```
    <tankThickness unit="mm"> 10 </tankThickness>
```

```
  </detector>
```

```
</detectorList>
```

Vertical muon starting at z=2 m

Use your own values

edit the input file

```
# vim muon.txt
```

```
5 0 0 1 0 0 0 0 0 0 0
```



1 muon+ with Pz=5 GeV/c
(add one line per secondary for multiple particles)

edit the G4WCDSimulator.json

```
"InputFileName" : "./muon.txt"  
(...)  
"DetectorList" : "./DetectorList.xml",  
(...)  
"GeoVisOn" : true,  
"TrajVisOn" : true,  
(...)
```

our file

our detector

enable vis output

run the simulation (~ 7 s in my notebook)

```
# ./G4WCDSimulator -c G4WCDSimulator.json
```

```
# ll
```

```
(...)
```

```
-rw-r--r-- 1 root root 34403 Nov 17 19:16 g4_00.wrl
```

```
-rw-r--r-- 1 root root 24 Nov 17 19:09 muon.txt
```

```
-rw-r--r-- 1 root root 177 Nov 17 19:16 output.json.gz
```

```
(...)
```

open a new terminal and copy the .wrl file

```
$ asoreyh@caronte:~$ docker ps
```

CONTAINER ID	IMAGE	COMMAND	CREATED	STATUS	PORTS	NAMES
7b1d505586d8	asoreyh/meiga:dev	"bash"	18 minutes ago	Up 18 minutes		beautiful_albattani

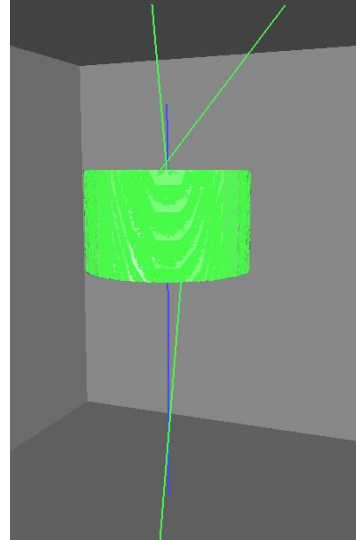
```
$ docker cp beautiful_albattani:/opt/meiga/build/Applications/G4WCDSimulator/g4_00.wrl .
```

```
Successfully copied 2.05kB to /home/asoreyh/.
```

```
$ view3dscene g4_00.wrl
```

if the viewer is not installed (in ubuntu):

```
$ sudo apt install view3dscene
```



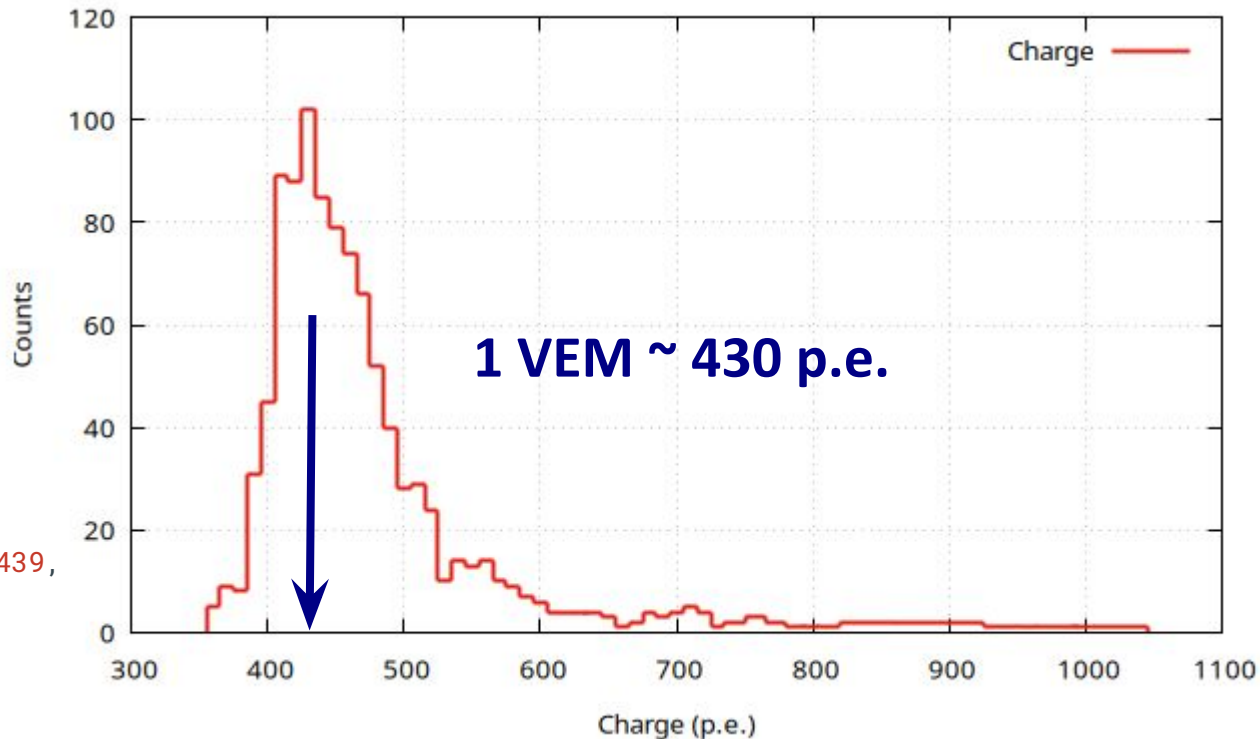
Problem 1: VEM charge distribution

Let's use, say, $N=1000$ vertical muons for calculating the VEM charge equivalent. For doing this:

1. Edit the muon.txt accordingly and run the simulation again.
2. Edit the config file for turning off the visualization outputs (Set GeoVision and TrajVision to false), and use the "eFast" mode
3. Run the simulation. It should take ~ 3 minutes
4. From the host terminal, copy the output.json.gz
5. Get the histograms of charge and deposited energy

Get the charge

```
(...)  
"Event_3": {  
  "InputFlux": {  
    "ID": -13,  
    "Position": [0.0, 0.0, 2000.0],  
    "Momentum": [0.0, 0.0, -5000.0]  
  },  
  "Detector_0": {  
    "EnergyDeposit": 195.0362666897439,  
    "OptDevice_0": {  
      "Charge": 475  
    }  
  }  
},  
(...)
```

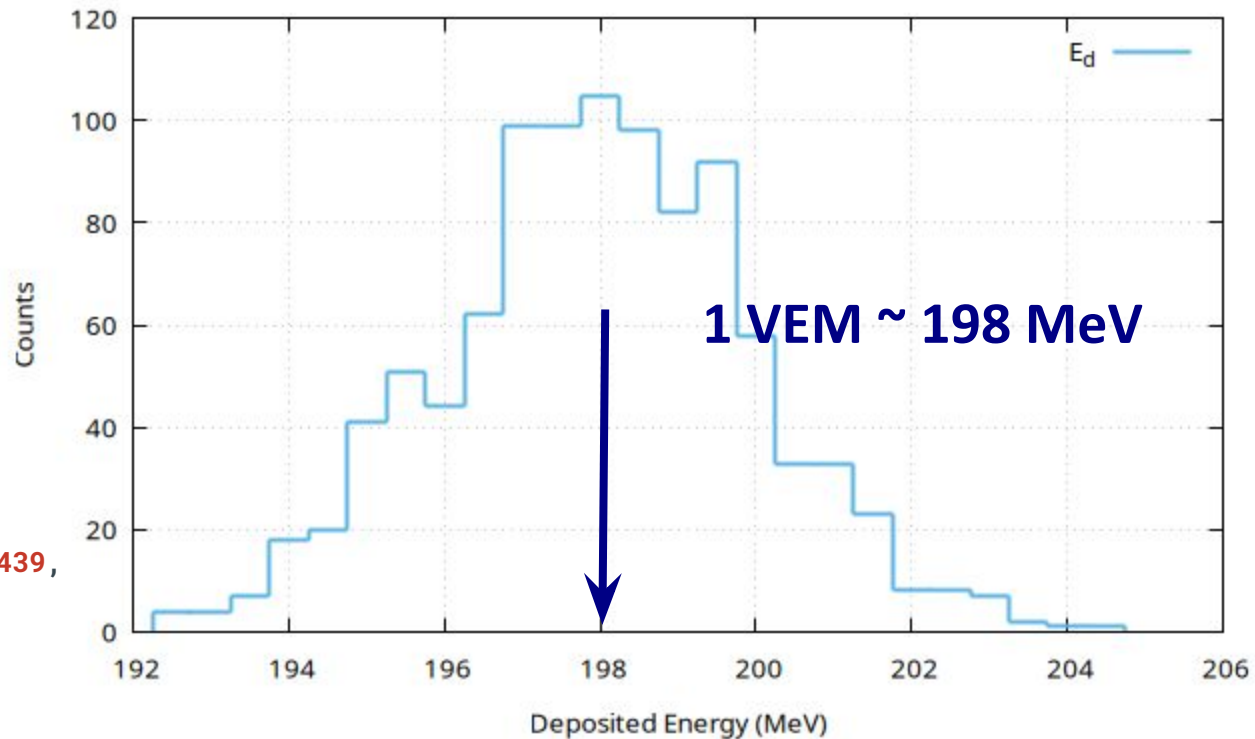


For example, in your terminal:

```
$ zcat output.json.gz | jq | grep "Charge" | awk '{b=5; print int($2/b)*b}' | sort -n | uniq -c >  
charge.dat
```

Get E_d

```
(...)  
"Event_3": {  
  "InputFlux": {  
    "ID": -13,  
    "Position": [0.0, 0.0, 2000.0],  
    "Momentum": [0.0, 0.0, -5000.0]  
  },  
  "Detector_0": {  
    "EnergyDeposit": 195.0362666897439,  
    "OptDevice_0": {  
      "Charge": 475  
    }  
  }  
},  
(...)
```



For example, in your terminal:

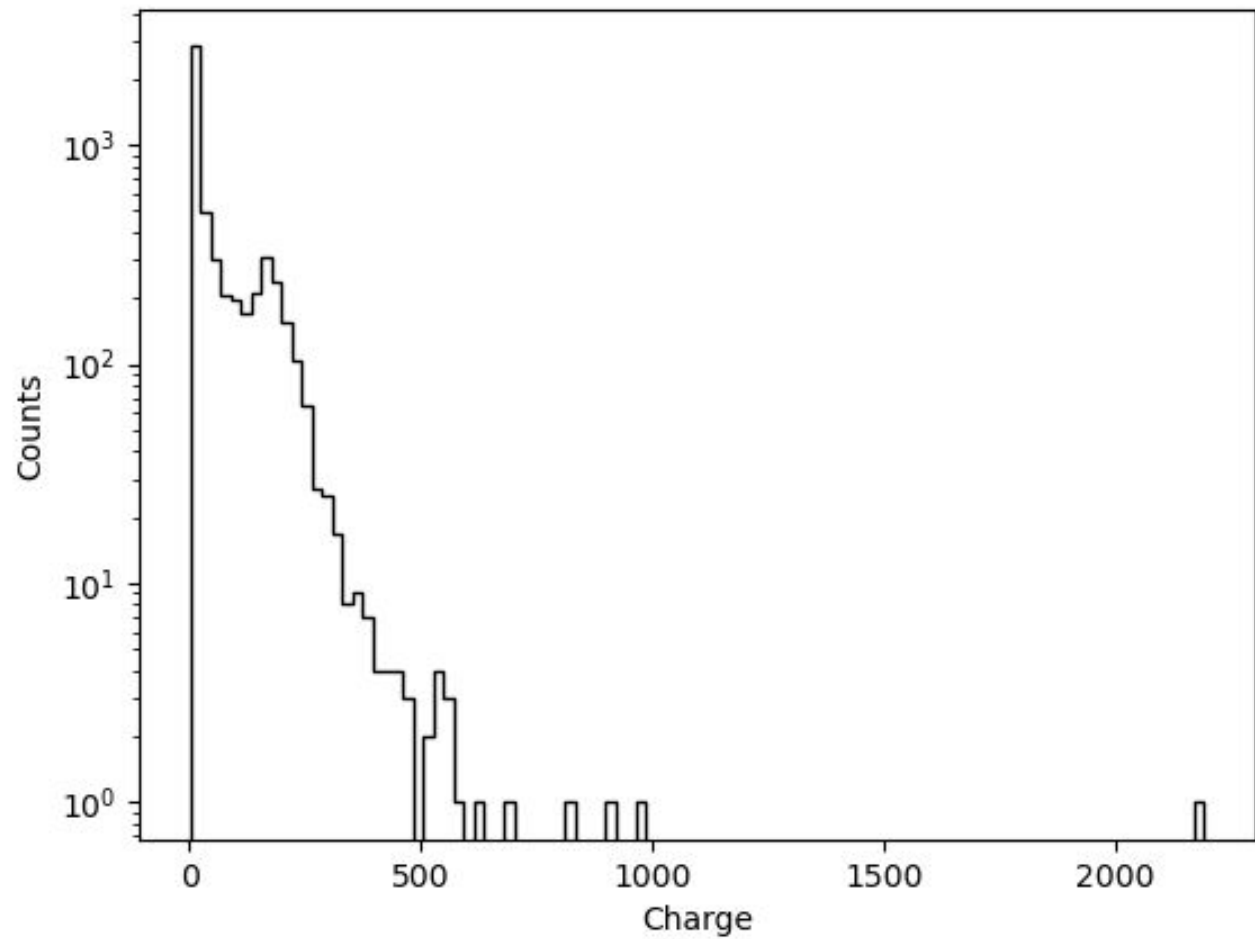
```
$ zcat output.json.gz | jq | grep "EnergyDeposit" | awk '{b=0.5; print int($2/b)*b}' | sort -n |  
uniq -c > ed.dat
```

Problem 2: Sample flux (at home)

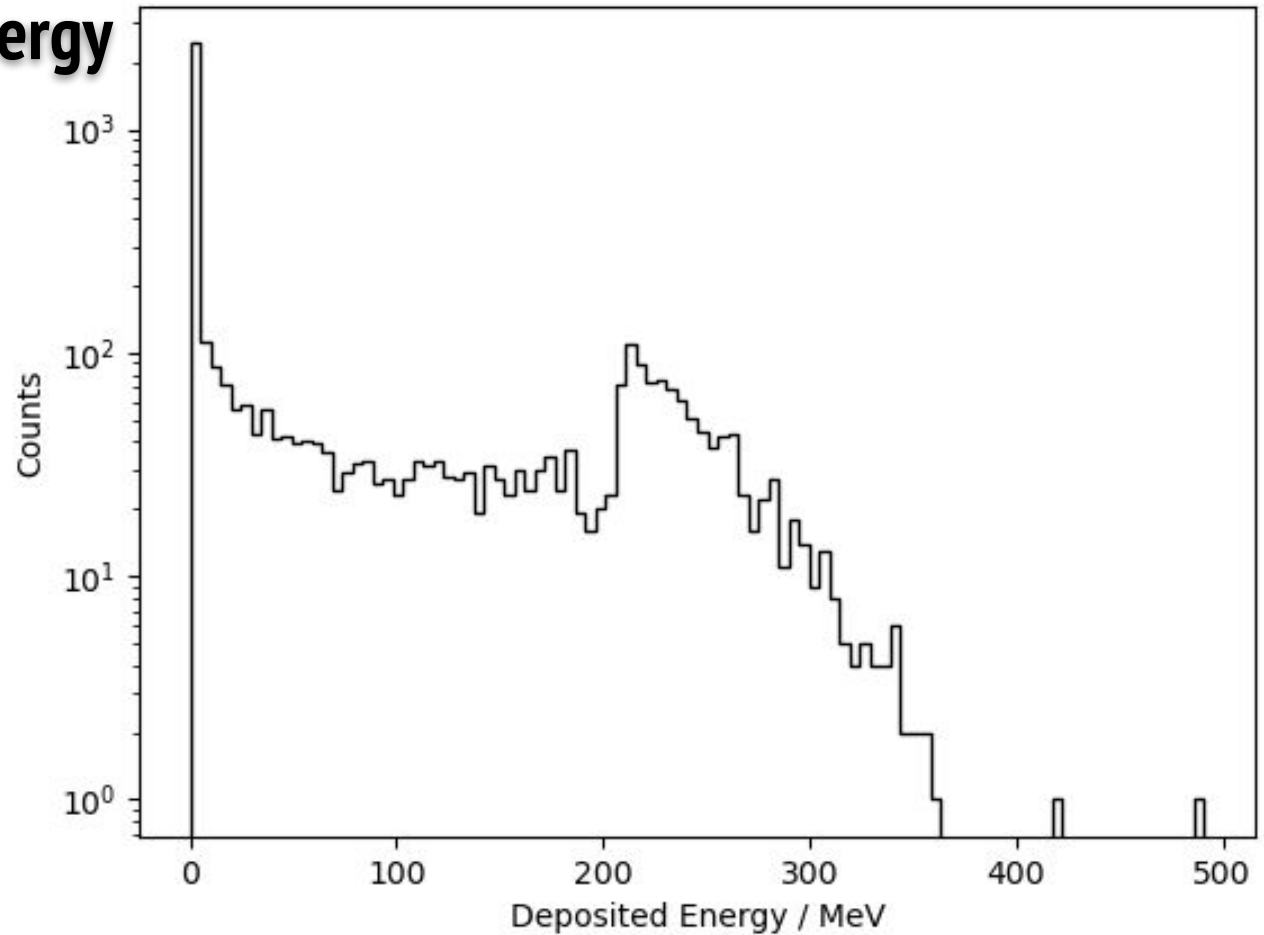
In `meiga/src/Documentation/SampleFlux/`, we included a sample for the BGA background calculated using ARTI (~34k part). Let's see the expected charge histogram:

1. Edit the config file for using this input (be sure "eFast" is selected):
`'/opt/meiga/src/Documentation/SampleFlux/salida_bga_30.shw'`
2. Edit the `DetectorList.xml` for using the "eCircle" mode: radius and height should be at least 2x the `tankRadius` and `tankHeight` (the larger the better, but... time)
3. Run the simulation. It should take ~ 6 minutes
4. From the host terminal, copy the `output.json.gz`
5. Get the histograms of charge and deposited energy

Charge

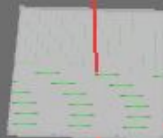
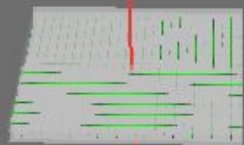


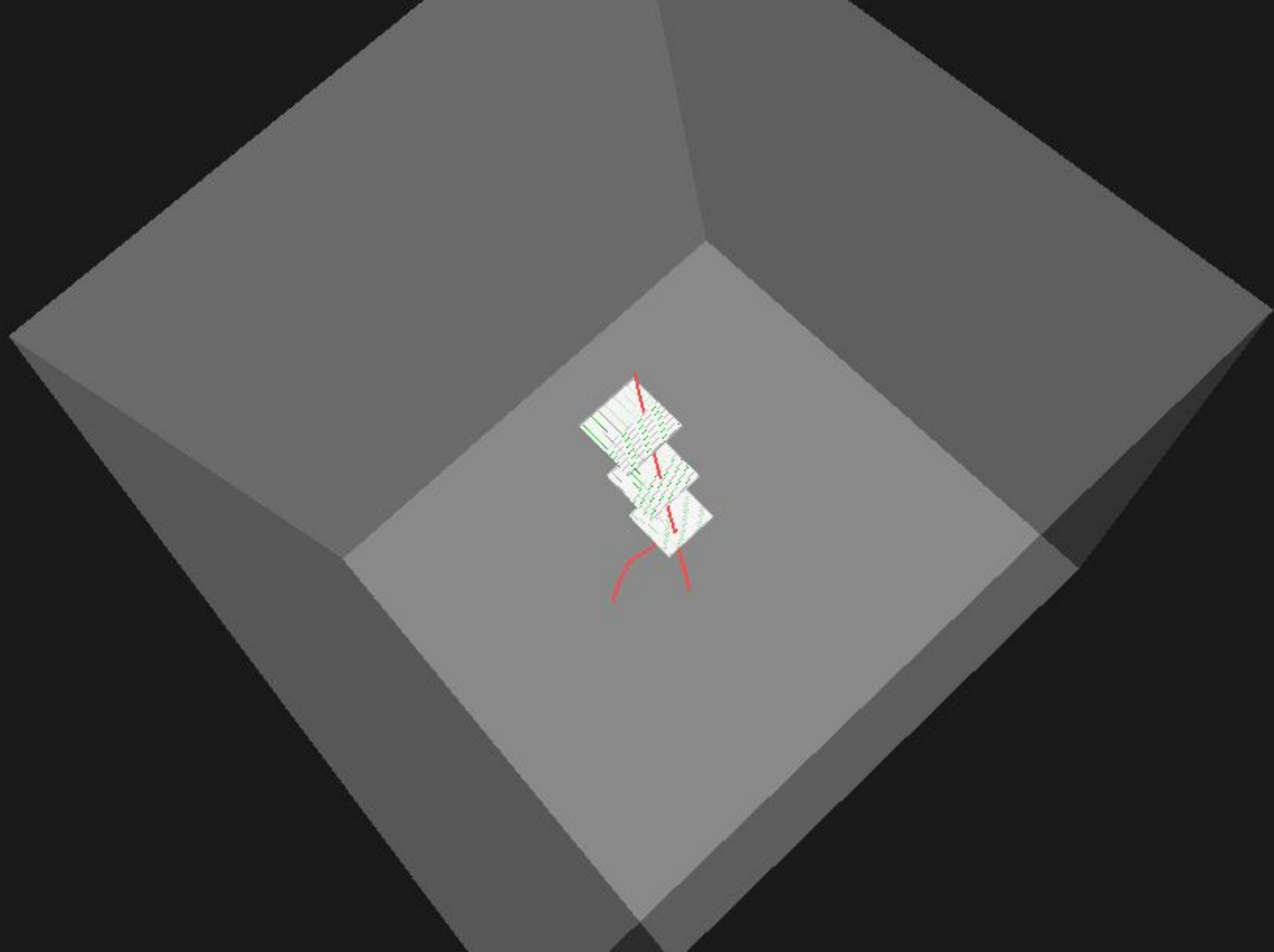
Deposited energy



Problem 3: Explore G4HodoscopeSimulator (at home)

1. Take a look to the files in the directory: what similarities do you observe with G4WCDSimulator? what differences?
2. From what you learnt up to now and obtain a visualization of a muon event detected by the default hodoscope
3. Change the default hodoscope for a Mute2.0-like hodoscope and obtain a new visualization
4. Get the panels hits for a 10k muon flux for Mute2.0

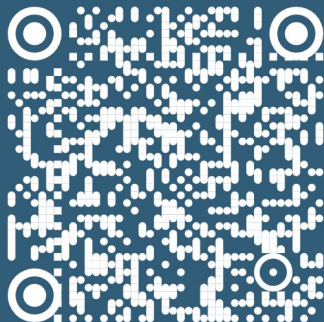




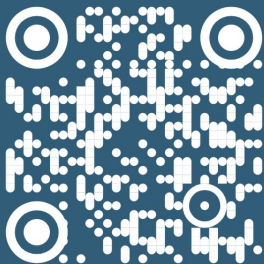
That's all Folks!



Comisión Nacional de Energía Atómica



this talk



contact me



LAGO INDICA

EOSC, MEIGA y Muongrafía

Hernán Asorey^{1,2} for the LAGO Collaboration

BGA, Colombia, 20/Nov/2024

Thanks!

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